

Charged beam acceleration

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Charged beam acceleration

1. How to accelerate a charged particle ?
2. RF accelerating cavity basics
3. Synchronism & stability
4. Introduction to longitudinal dynamics

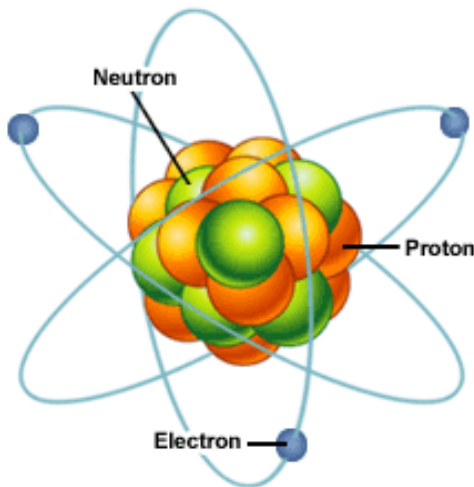
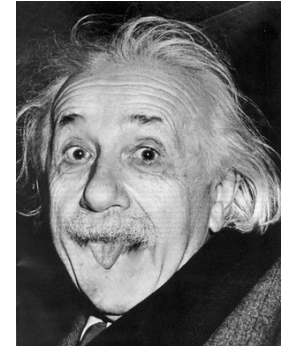
1. How to accelerate a charged particle ?

1.1. Mass of a particle at rest

- Rest mass =>

$$E_0 = m_0 c^2$$

(1905)



avec

m_0 : particle mass (kg)

$c \approx 2.998 \times 10^8$ m/s : speed light

ex :

electrons : $E_0 \approx 511$ keV

protons : $E_0 \approx 938.3$ MeV

heavy ions : $E_0 \approx A \times \text{uma}$

(1 uma ≈ 931.5 MeV, A : nb nuclei)

- **1 eV** (électron-volt) = energy gained by a particle with elementary charge $e = 1.602 \times 10^{-19}$ C (ex: electron, proton) seeing a 1 Volt voltage

$$\underline{1 \text{ eV} \Leftrightarrow 1.602 \times 10^{-19} \text{ J}}$$

1.2. Mass of a travelling particle

- **Total energy** =>

$$E_{\text{tot}} = \gamma m_0 c^2$$

avec

γ : reduced energy/mass

β : reduced speed

v : particle speed

$$\gamma = \frac{E_{\text{tot}}}{E_0} = \frac{m}{m_0} = \frac{1}{\sqrt{1 - \beta^2}}$$

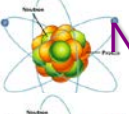
$$\beta = \frac{v}{c}$$

- **Kinetic energy**

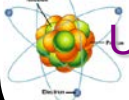
$$\Rightarrow E_{\text{cin}} = E_{\text{tot}} - E_0 = (\gamma - 1) m_0 c^2$$



Rest particle => $\beta = 0$, $\gamma = 1$



Non-relativistic particle => $\beta \ll 1$, $\gamma \approx 1$



Ultra-relativistic particle (approaching the speed of light) => $\beta \rightarrow 1$, $\gamma \rightarrow \infty$

1.3. Momentum of a particle

- **Momentum**

$$\Rightarrow p = mv = \beta\gamma m_0 c$$

- **Useful relation between energy & momentum ?**

$$\begin{aligned} E_{\text{tot}}^2 - E_0^2 &= (\gamma^2 - 1) E_0^2 \\ &= (\beta\gamma)^2 m_0^2 c^4 = p^2 c^2 \end{aligned}$$

energy : MeV $\Rightarrow$ momentum : MeV/c

$$E_{\text{tot}}^2 - E_0^2 = p^2 c^2$$

- **Kinetic energy in the non-relativistic approximation ?**

$$E_{\text{cin}} \ll E_0, \gamma \approx 1$$

$$p^2 c^2 = E_{\text{tot}}^2 - E_0^2 = (E_{\text{tot}} - E_0)(E_{\text{tot}} + E_0) = E_{\text{cin}}(2E_0 + E_{\text{cin}}) \cong 2E_0 E_{\text{cin}}$$

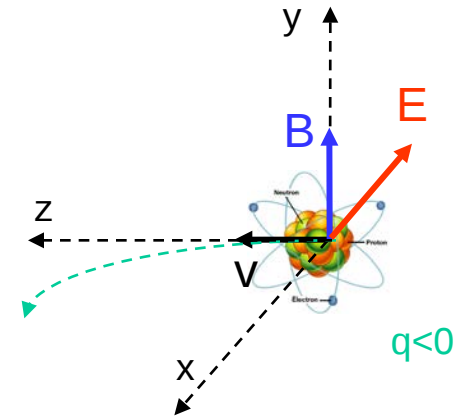
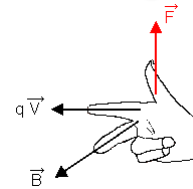
$$\text{Thus } E_{\text{cin}} \cong \frac{p^2 c^2}{2E_0} = \frac{m_0^2 v^2 c^2}{2m_0 c^2} = \frac{1}{2} m_0 v^2$$



1.4. Lorentz force

The movement of a charged particle in an electromagnetic field is described by:

$$\frac{d\vec{p}}{dt} = \vec{F} = q (\vec{E} + \vec{v} \wedge \vec{B})$$



where $\vec{F}$: Lorentz force (N)

q : particle charge (C)

$\vec{E}$ & $\vec{B}$: electric & magnetic fields (V/m, T)

$\vec{p}$: momentum (kg.m/s) $\rho = m v = \beta \gamma m_0 c$

Remark: B is actually the magnetic induction

$\vec{B} = \mu_0 \vec{H}$ in vacuum, where H : magnetic field (A/m)

$\mu_0 = 4\pi \times 10^{-7}$: vacuum permeability (H/m)

$\epsilon_0 = \frac{1}{\mu_0 c^2}$: vacuum permittivity (C²/N/m²)

1.5. Acceleration of a charged particle

- Effect of the Lorentz force on the energy of a charged particle

$$\begin{aligned}\vec{p} \cdot \frac{d\vec{p}}{dt} &= \frac{1}{2} \frac{dp^2}{dt} = \frac{1}{2c^2} \frac{dE_{\text{tot}}^2}{dt} = \frac{E_{\text{tot}}}{c^2} \frac{dE_{\text{tot}}}{dt} = \gamma m_0 \frac{dE_{\text{tot}}}{dt} \\ &= \gamma m_0 \vec{v} \cdot q (\vec{E} + \vec{v} \wedge \vec{B}) = \gamma q m_0 \vec{v} \cdot \vec{E}\end{aligned}$$



$$\boxed{\frac{dE_{\text{tot}}}{dt} = q \vec{v} \cdot \vec{E}}$$

- In order to accelerate / gain some energy:

- Only the electric field is useful
- If $\vec{E} \perp \vec{v}$, NO acceleration
- If $\vec{E} // \vec{v}$, optimum acceleration

This is
ELECTROSTATIC
acceleration

=> Energy gain ΔE_{tot} in a static electric field :

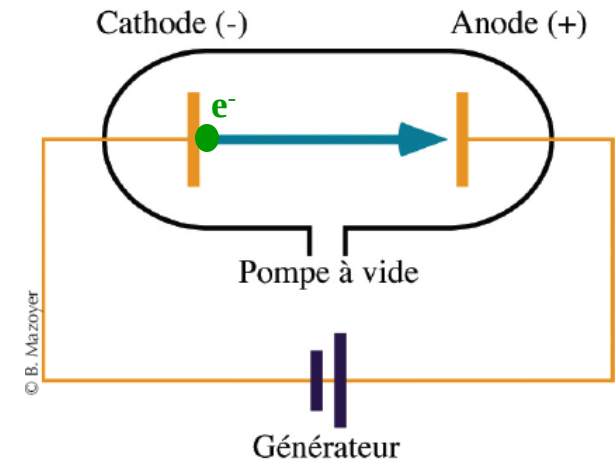
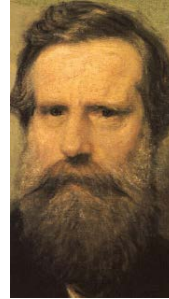
$$\Delta E_{\text{tot}} = qE \int v dt = qE \Delta x = \underbrace{(q)}_{\text{Nb elementary charges}} \underbrace{\Delta V}_{\text{applied voltage (MV)}}$$

(MeV)

1.6. Early electrostatic experiments: vacuum tubes

1875: W. Crookes experiment

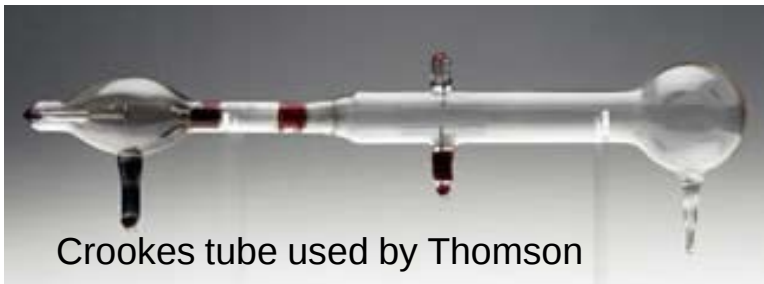
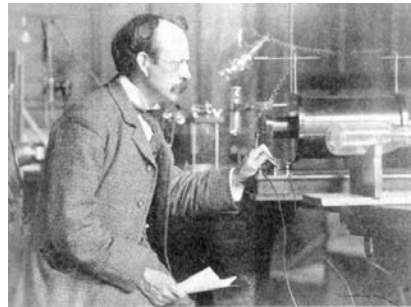
Study of the influence of air density on the voltage to be applied between two electrodes to create an electric discharge



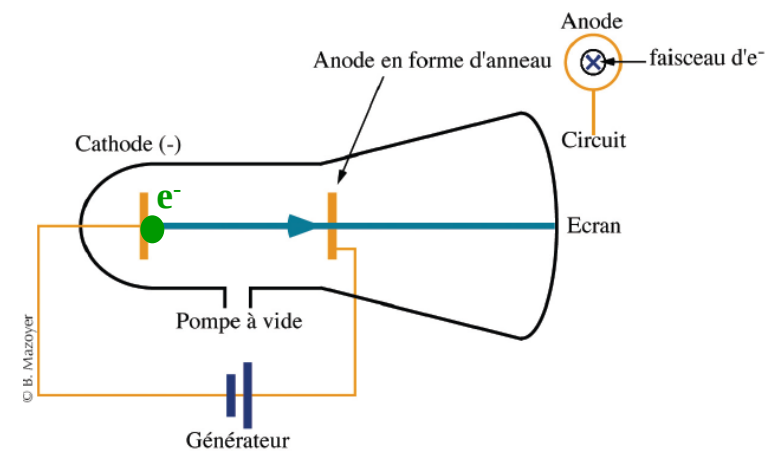
1897 : J.J. Thomson experiment

Perforated anode, phosphorescent screen, & magnetic coils, 300 V voltage

=> Discovery of the electron !

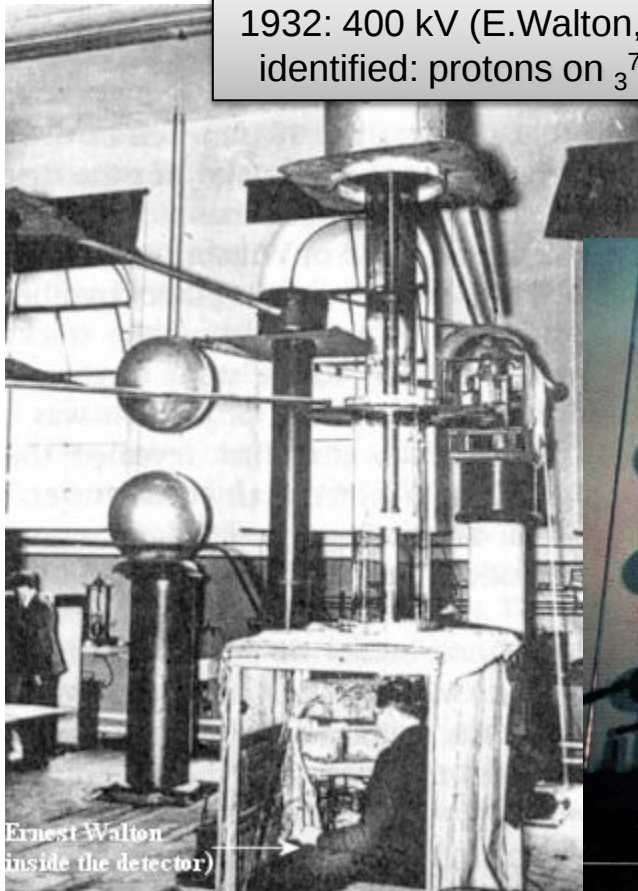


Crookes tube used by Thomson



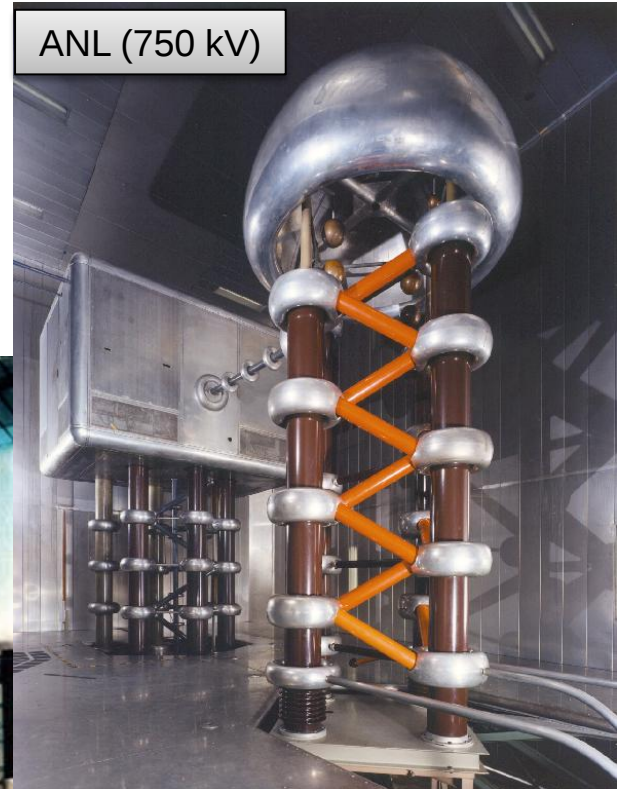
1.7. Example of electrostatic accelerators (1)

Cockcroft & Walton accelerators



1932: 400 kV (E. Walton, first fissions identified: protons on ${}_3^7\text{Li} \rightarrow {}_2^4\text{He}$)

Ernest Walton
(inside the detector)

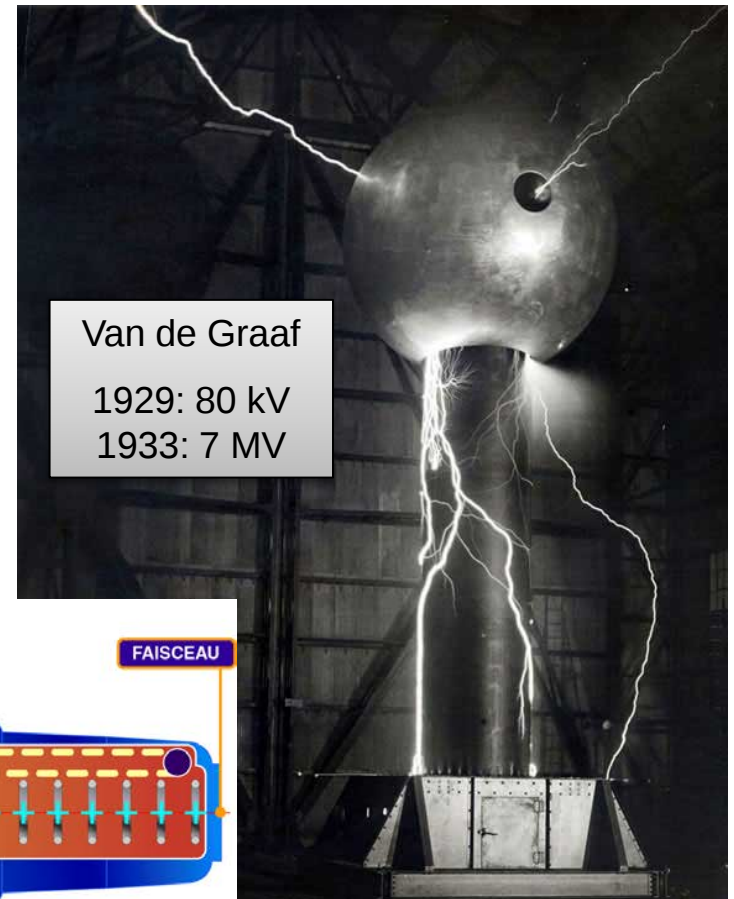


ANL (750 kV)

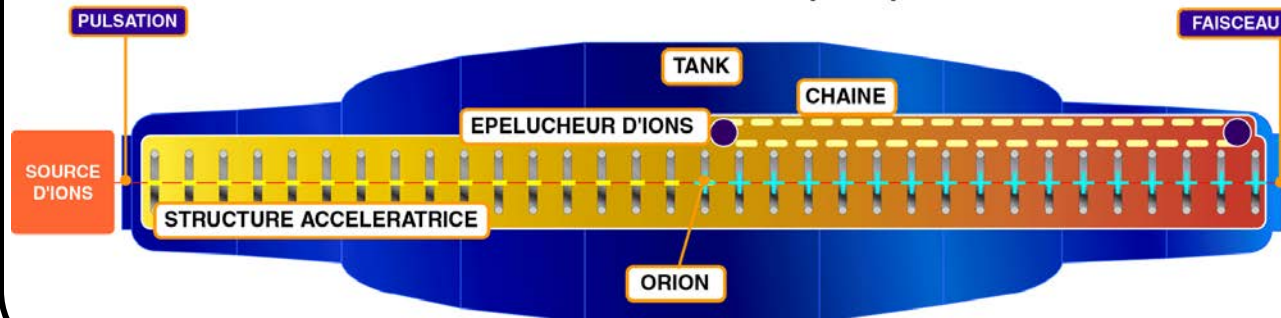
PSI (800 kV)

1.7. Example of electrostatic accelerators (2)

Van de Graaf accelerators & Tandems



TANDEM : Schéma de principe



1.8. From electrostatic to RF acceleration

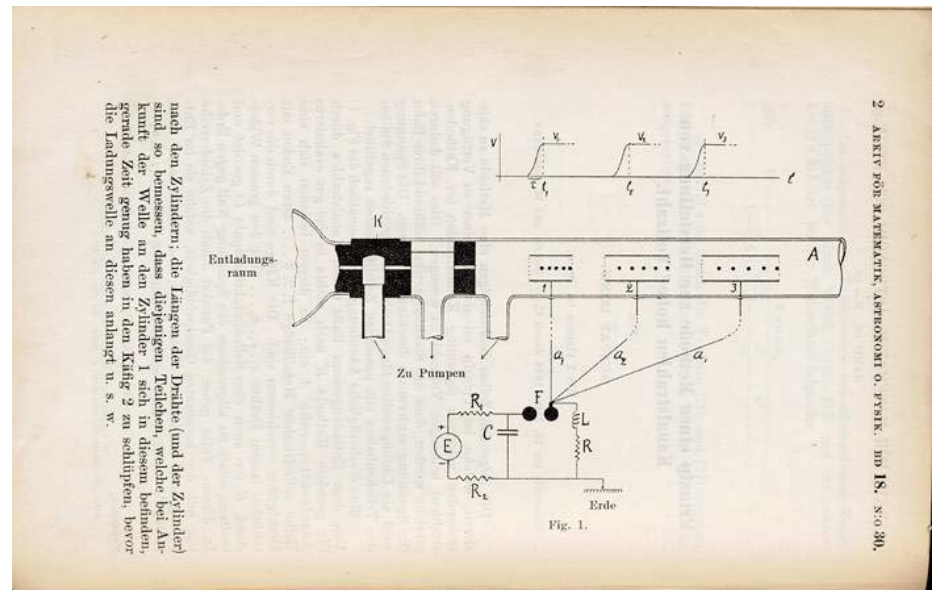
Limitation of electrostatic acceleration:

The beam energy gain is directly proportional to the voltage being applied between the 2 electrodes of the system. This concept is limited by electrostatic breakdown... that means up to a few MV in the best case...

1924: G. Ising paper

1st step towards RF acceleration: given the electrostatic limitations, Ising proposes to give the energy to the particle using several modest accelerations instead of one single large one. The concept of RF acceleration is born.

This concept is presently used in all modern large accelerators

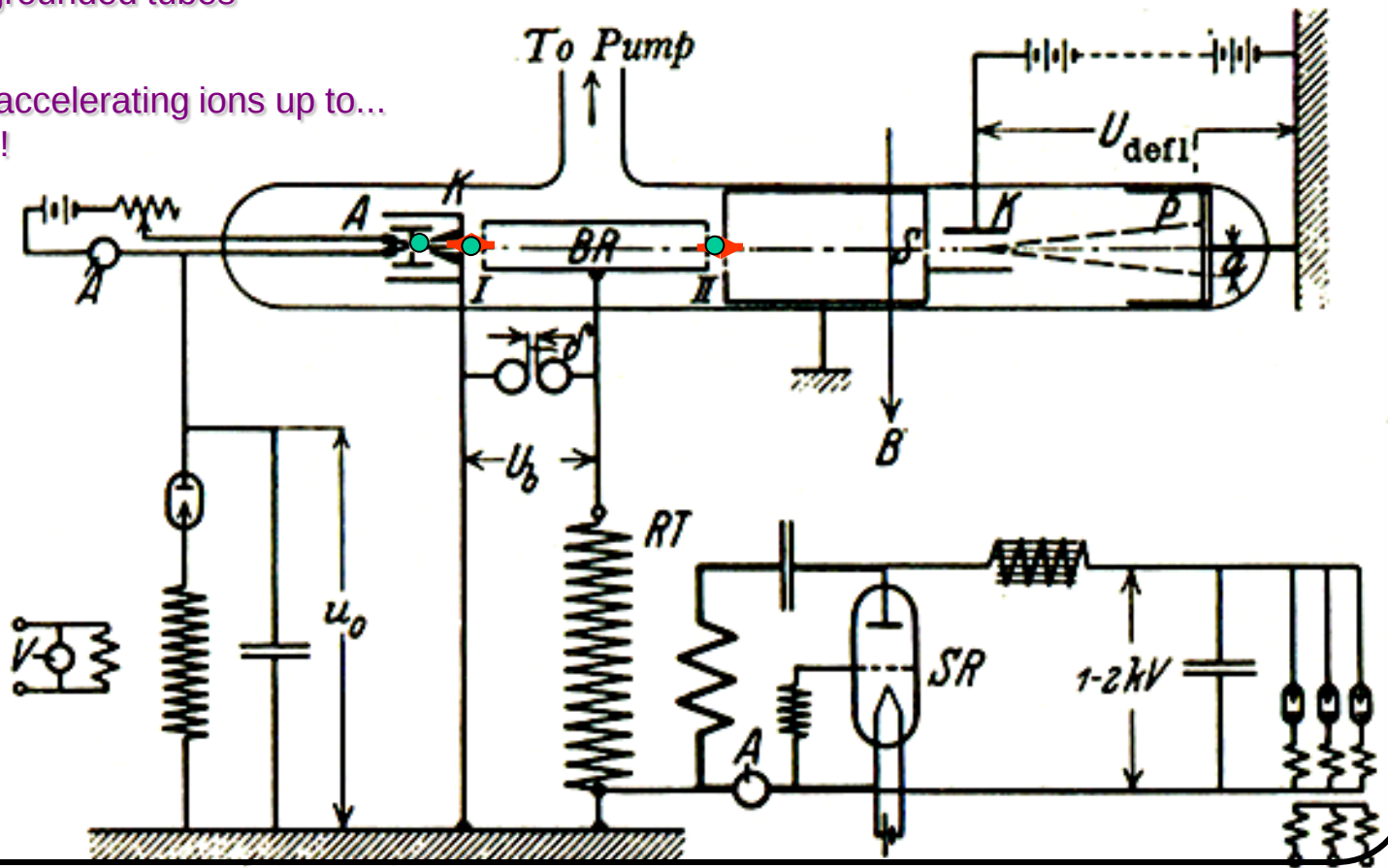


1.9. Wideröe experiment

1928: R. Wideröe experiment

First experimental proof of RF acceleration: an alternating AC voltage of 25kV is applied to a drift tube located between 2 grounded tubes

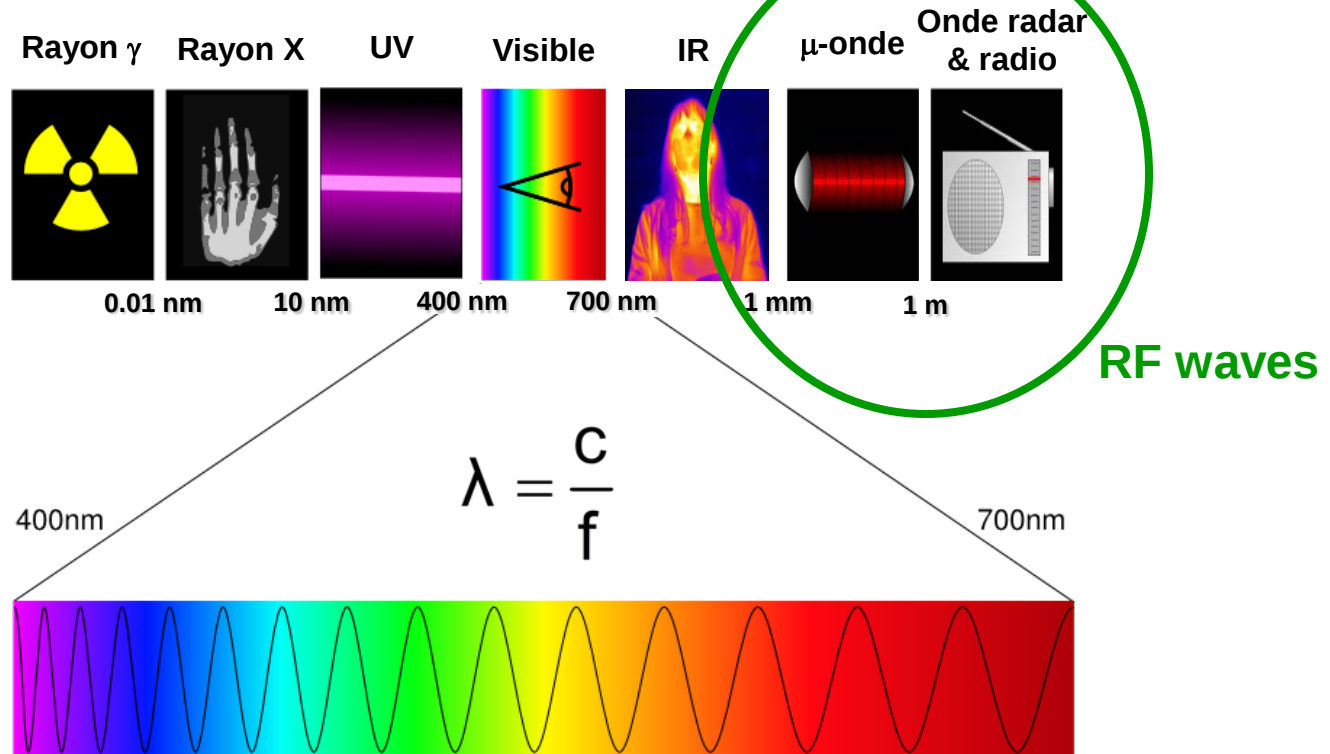
=> He succeeded in accelerating ions up to...
... $2 \times 25 = 50$ keV !



2. RF accelerating cavity basics

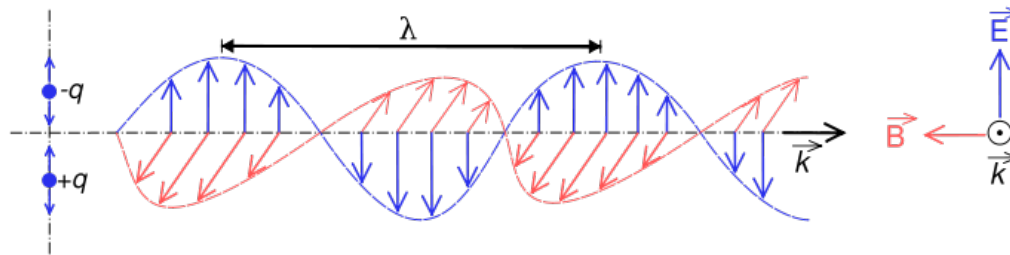
2.1. RF waves

- A **radio-frequency (RF) wave** is an electromagnetic wave whose frequency (f) is, by convention, **between 9 kHz and 3000 GHz**, that corresponds to wavelengths (λ) between 33 km and 0,1 mm.



2.2. Maxwell equations

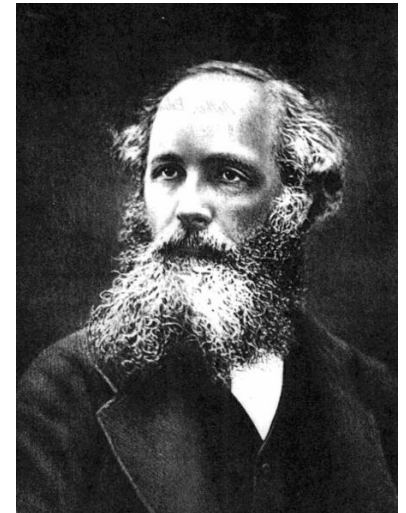
- **Electromagnetic wave** = coupled oscillation of electric and magnetic fields, traveling in vacuum with the speed of light



- **The evolution of electric & magnetic fields are linked by Maxwell equations (1873)**

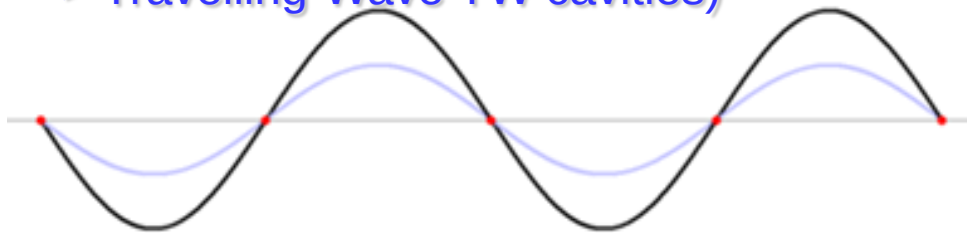
$$\left\{ \begin{array}{ll} \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} & \text{Gauss law (links electric charge \& electric field)} \\ \vec{\nabla} \cdot \vec{B} = 0 & \text{(no "magnetic charge", no single magnetic pole)} \\ \vec{\nabla} \wedge \vec{B} = \mu_0 \left(\vec{j} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) & \text{Ampere law (links electric current \& magnetic field)} \\ \vec{\nabla} \wedge \vec{E} = -\frac{\partial \vec{B}}{\partial t} & \text{Faraday law (interaction between electric \& magnetic field)} \end{array} \right.$$

where ρ : charge density (C/m³) & j : current density (A/m²)



2.3. Resonant RF cavities

- **Resonant cavity** = volume of dielectric material (usually = vacuum) surrounded by conductive walls, in which the electromagnetic waves are being reflected, creating an array of electromagnetic fields, oscillating at several frequencies with various spatial configurations
=> possibility to create **stationnary waves** -> **Standing-Wave SW cavities**
- (but note that progressive EM waves can also be used, especially for electrons -> Travelling-Wave TW cavities)



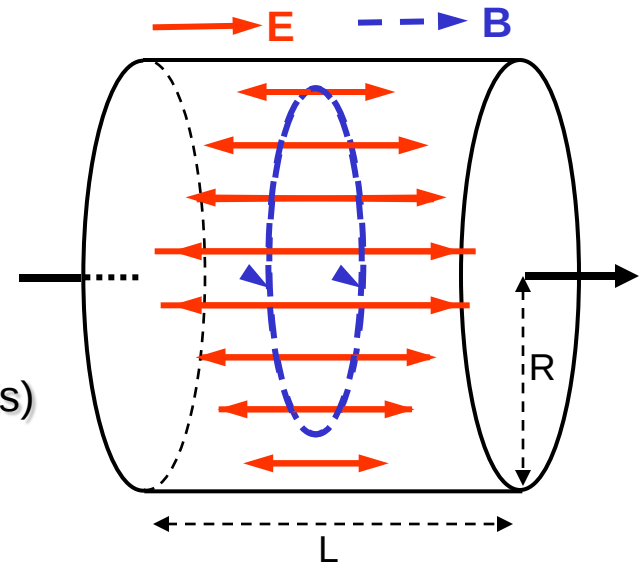
- **Ex: “pillbox” cavity of length L et radius R**

=> RF frequency of the “accelerating mode” (E on beam axis)

$$f_{TM010} = \frac{2.405c}{2\pi R}$$

Ex : $f = 700 \text{ MHz} \rightarrow R = 16.4 \text{ cm}$

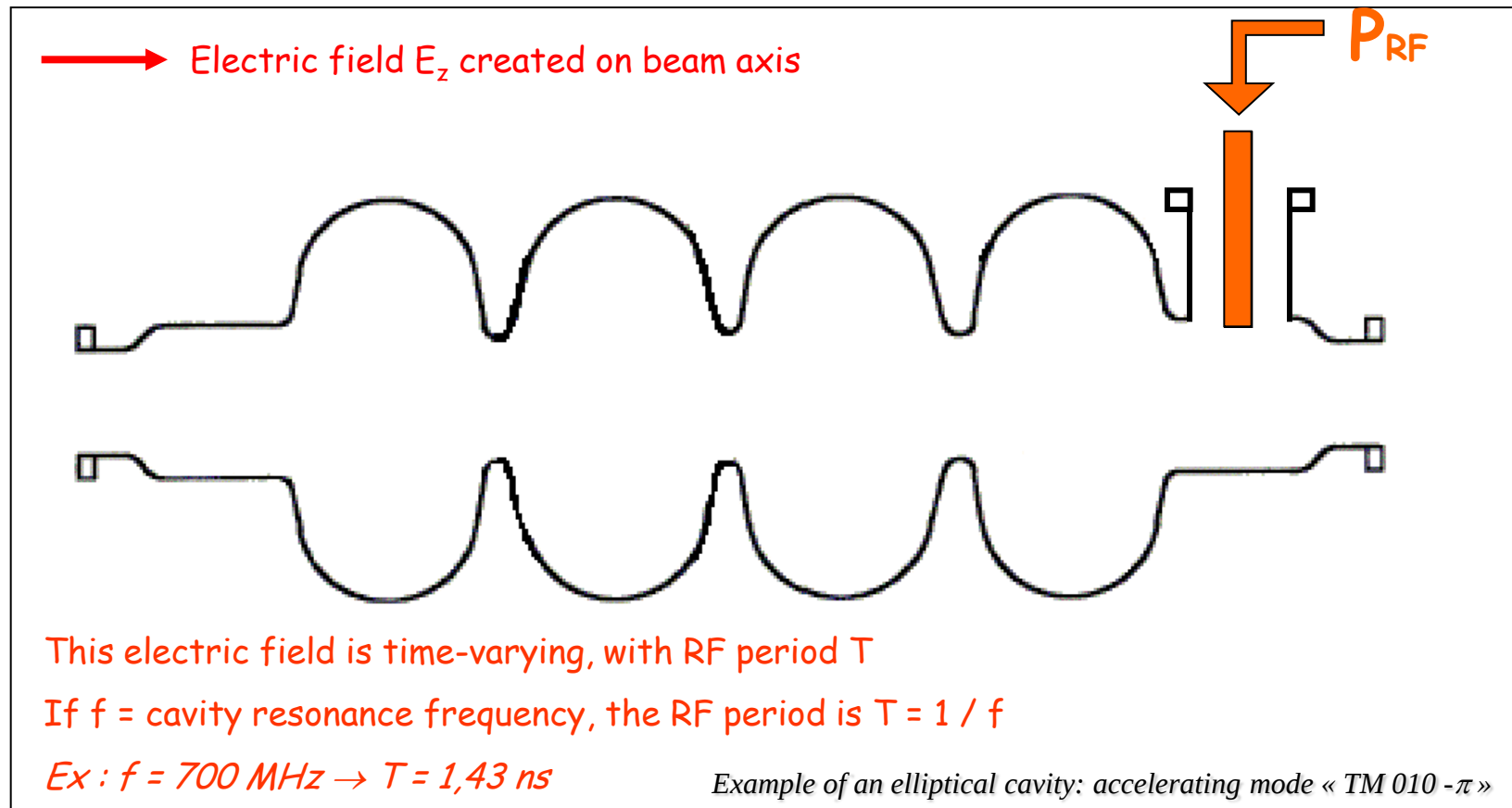
LOW frequency = BIG cavity !



« Pill-box » cavity : TM 010 mode

2.4. Principle of an accelerating RF cavity (1)

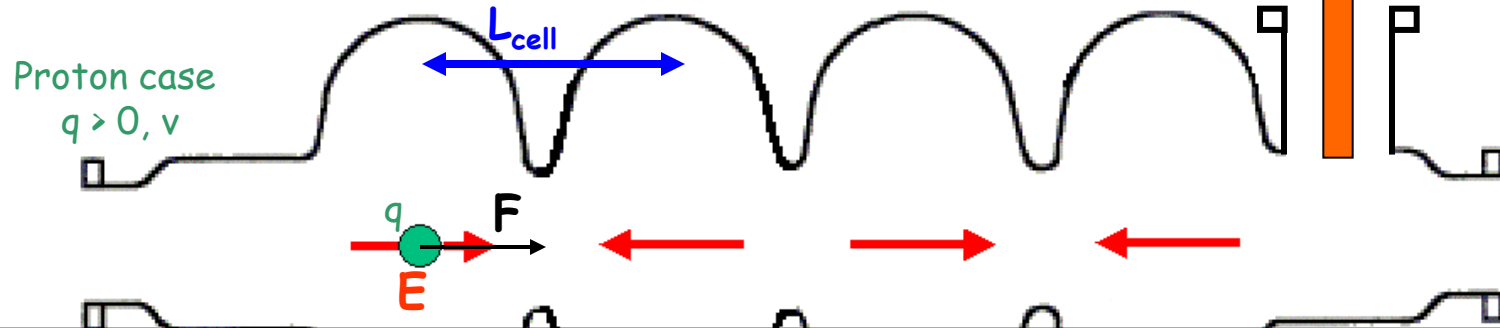
- (1) Creation of a radio-frequency (RF) electric field on beam axis, that can be used to accelerate charged particles



2.4. Principle of an accelerating RF cavity (2)

- (2) A charged particle is arriving : for an efficient acceleration, electromagnetic fields need to be correctly synchronised with the particle we want to accelerate

The force leading to acceleration $\vec{F} = q \cdot \vec{E}$ needs to be correctly oriented



Synchronization condition :

The charged particle needs to travel from one cell to another cell in $T_{RF}/2 \Leftrightarrow \frac{L_{cell}}{v} = \frac{1}{2f}$

The cell length has therefore to verify: $L_{cell} = \frac{v}{2f} = \frac{\beta c}{2f}$ or $L_{cell} = \frac{\beta \lambda}{2}$

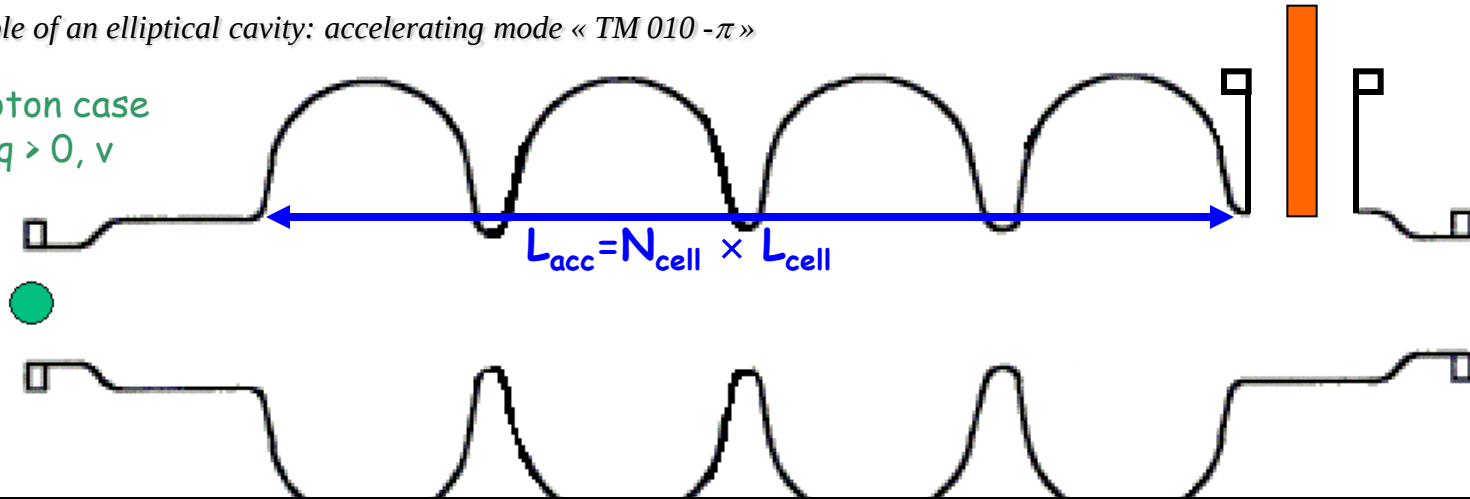
« The lower the particle speed, the lower L_{cell} and/or f »

Ex: $f = 700\text{MHz}$ & $\beta = 1 \Rightarrow L_{cell} = 21,4\text{ cm}$ (half for $\beta = 0,5$)

2.4. Principle of an accelerating RF cavity (3)

Example of an elliptical cavity: accelerating mode « TM 010 - π »

Proton case
 $q > 0, v$



Energy given to the particle :

$$\Delta W = q \times \int_{t_{\text{entrée}}}^{t_{\text{sortie}}} \vec{E} \cdot \vec{v} dt \quad \text{or} \quad \Delta W = q \times E_{\text{acc}} \times L_{\text{acc}} \times \cos(\varphi_s)$$

E_{acc} : accelerating field seen by the particle (for a particle with speed v)

L_{acc} : accelerating length of the cavity

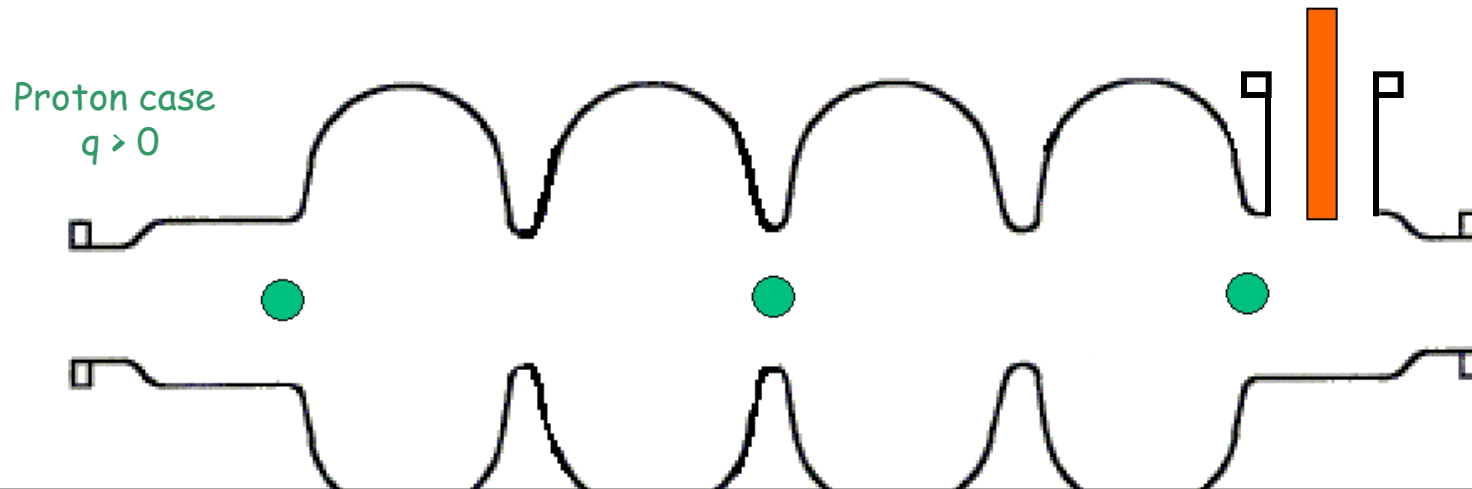
φ_s : synchronous phase particle / RF wave

Ex : $f = 700\text{MHz}$; 5-cell cavity $\beta = 0.65$; $E_{\text{acc}} = 10\text{MV/m}$; $\varphi_s = -30^\circ$

$\Rightarrow$ Energy gained : $\Delta W = 1\text{eV} \times 10\text{MV/m} \times 0,7\text{m} \times 0.87 = 6\text{ MeV}$

2.4. Principle of an accelerating RF cavity (4)

- (3) Beam acceleration : particles need to be grouped in bunches, correctly synchronized with the RF frequency



The time left between 2 bunches has to fit with the RF period (or with a multiple of it)

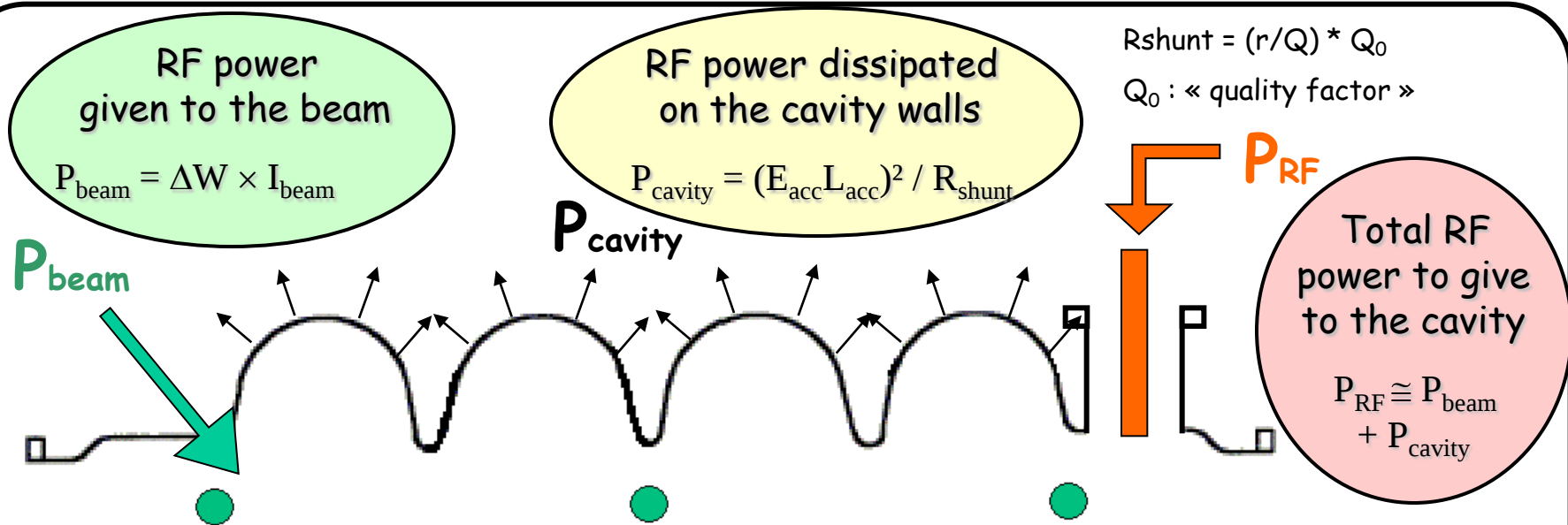
$$T_{\text{beam}} = n T_{\text{RF}} \quad (n=1,2,3\dots)$$

« The RF frequency of a resonant cavity needs to be an integer multiple of the repetition frequency of the beam it has to accelerate »

Ex: if $f_{\text{beam}}=350 \text{ MHz}$ ($T_{\text{beam}}=2,86\text{ns}$), thus the cavity needs to resonate with:

$f = 350 \text{ MHz}$ ($T_{\text{RF}}=2,86\text{ns}$), or $f = 700 \text{ MHz}$ ($T_{\text{RF}}=1,43\text{ns}$), or $f = 1050 \text{ MHz}$ ($T_{\text{RF}}=0,95\text{ns}$), etc.

2.5. Power balance in an accelerating cavity



Orders of magnitude (cavity 700 MHz - $\beta = 0.65$ - 5 cells - 10MV/m - $\varphi = -30^\circ$ - proton beam 10 mA)

SC cold cavity ($Q_0 \sim 10^{10}$): $P_{\text{beam}} = 6 \text{ MeV} \times 10 \text{ mA} = 60 \text{ kW}$
 $P_{\text{cavity}} \approx 16 \text{ W}$ to be evacuated at 4K (equiv. 4kW) or 2K (equiv. 10kW)

Room-temp. cavity ($Q_0 \sim 3 \cdot 10^4$): $P_{\text{beam}} = 60 \text{ kW}$ also
 $P_{\text{cavity}} \approx 5,5 \text{ MW} !!! \leftarrow \text{impossible in CW mode...!!!!}$

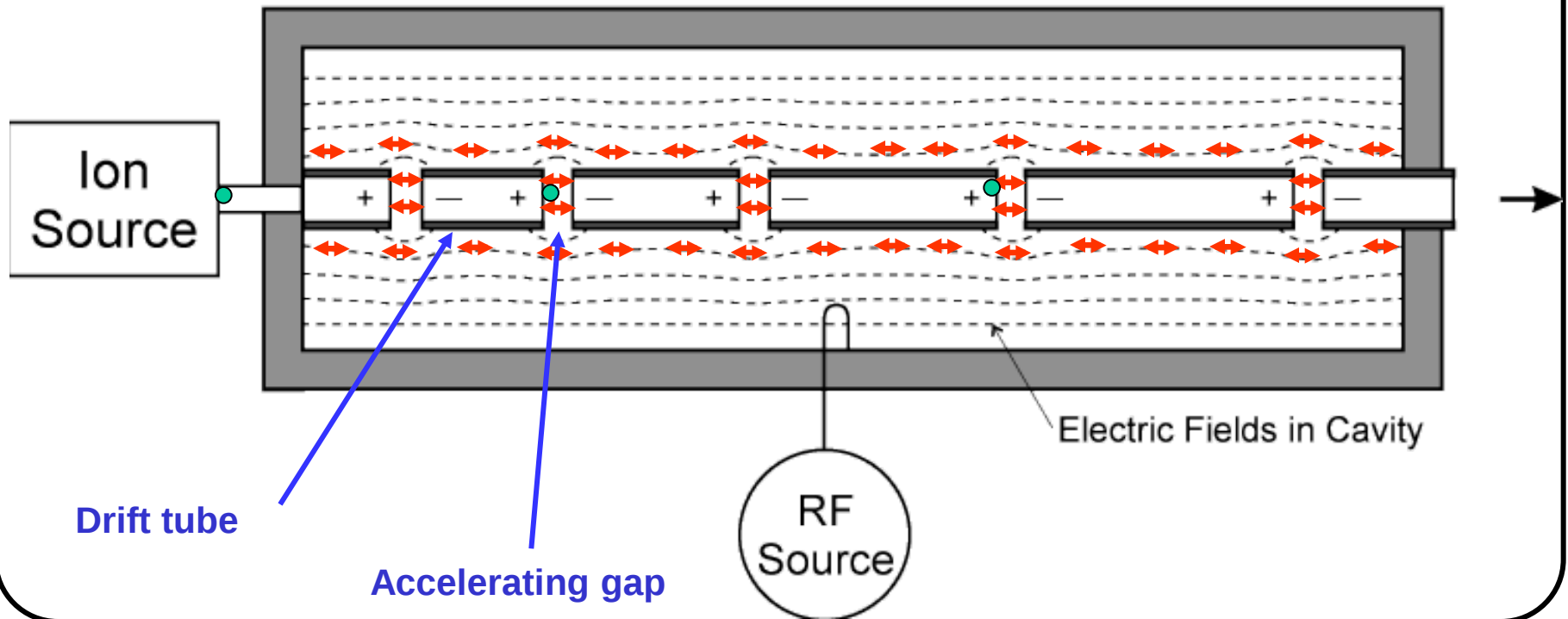
=> Need to limit the field or/and the RF duty cycle in room-temperature cavities

2.6. The first RF accelerating cavity

1946 : 1st proton linac by L.W. Alvarez

Alvarez DTL = long « pill-box » cavity where are inserted drift-tubes to hide the wrong polarity electric field from the beam; it operates on the $TM_{010-2\pi}$ mode

Possible thanks to new RF power sources developed during WW2 for military applications at $f > 10\text{MHz}$



2.7. RF structures Vs particle speed

Example :

Let's consider an electron (-1 eV)
& a proton (+1 eV) at rest, and let's give them
a net accelerating voltage of 10 MV

- **Energy gain** => 10 MeV in each case

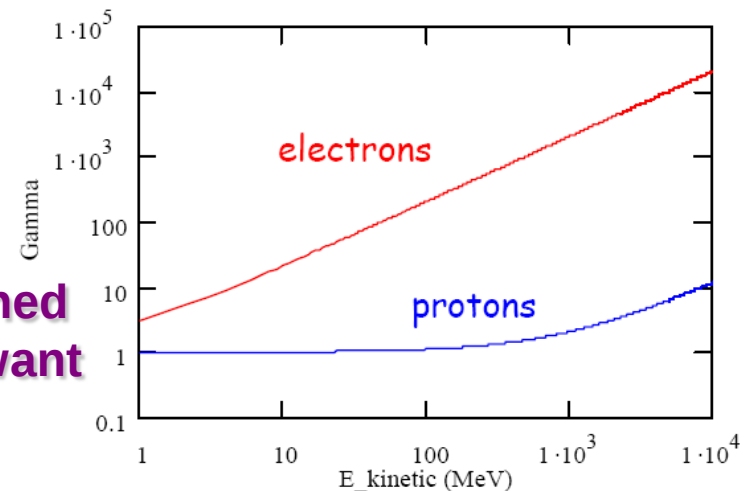
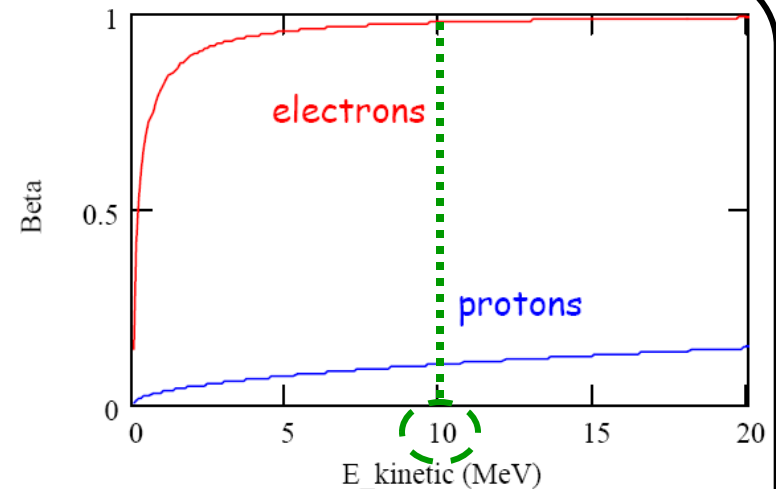
- **Speed gain**

electron $\gamma_e = 1 + \frac{E_{\text{cin}}}{m_0 c^2} = 1 + \frac{10}{0.511} \approx 20.6$

$$\beta_e = \sqrt{1 - \frac{1}{\gamma^2}} \approx 0.9988$$

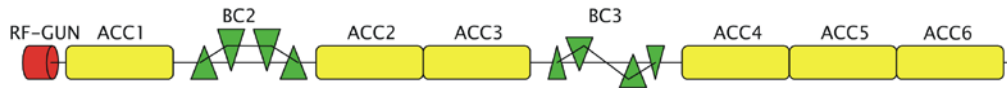
proton $\gamma_p = 1 + \frac{10}{938.3} \approx 1.01$ $\beta_p \approx 0.145$

**The accelerator structures have to be designed
to match the beta-profile of the particle we want
to accelerate !!!**

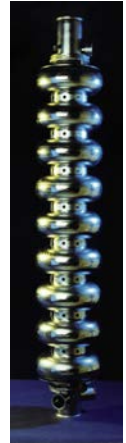


2.8. Electron Vs Proton linear accelerators

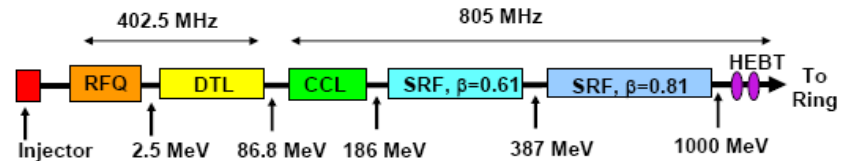
FLASH at DESY: 1.3 GeV electron linac, <100m



All RF cavities are practically similar:
1.3GHz $\beta=1$ elliptical cavities



SNS at ORNL: 1.0 GeV proton linac, >300m



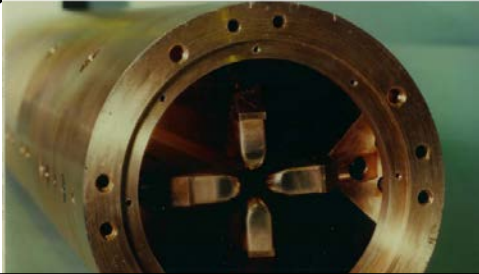
1 RFQ
6 DTL Tanks
4 CCL Modules

11 Medium- β Cryomodules - 3 Nb cavities each
12 High- β Cryomodules - 4 Nb cavities each

A lot of different RF structures...!!



2.9. Examples of RF accelerating cavities (1)

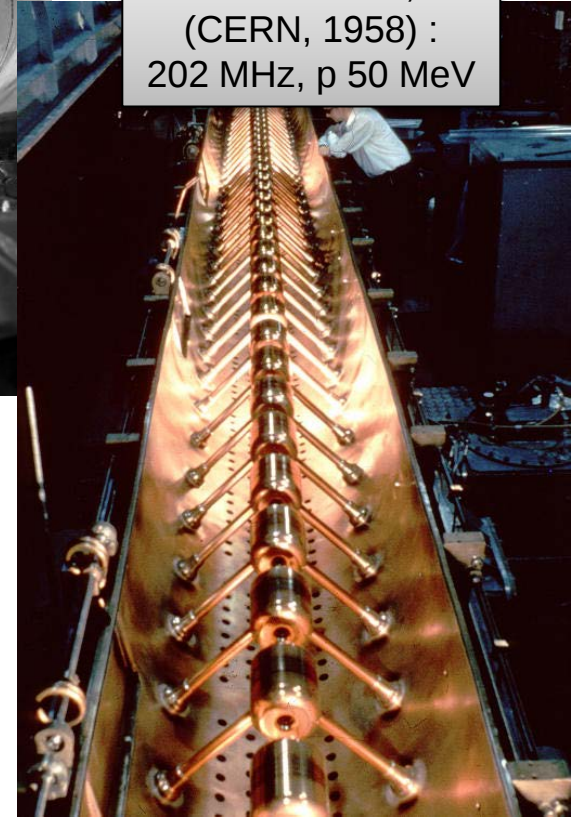


1st RFQ (LANL, 1980) :
p 100->640 keV, 425 MHz

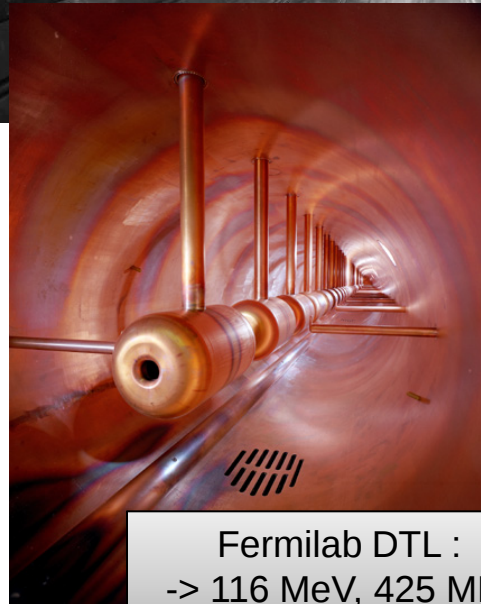
The original Alvarez DTL (Berkeley, 1946) :
200 MHz, p 4->32 MeV, 12 m



DTL Linac 1,
(CERN, 1958) :
202 MHz, p 50 MeV

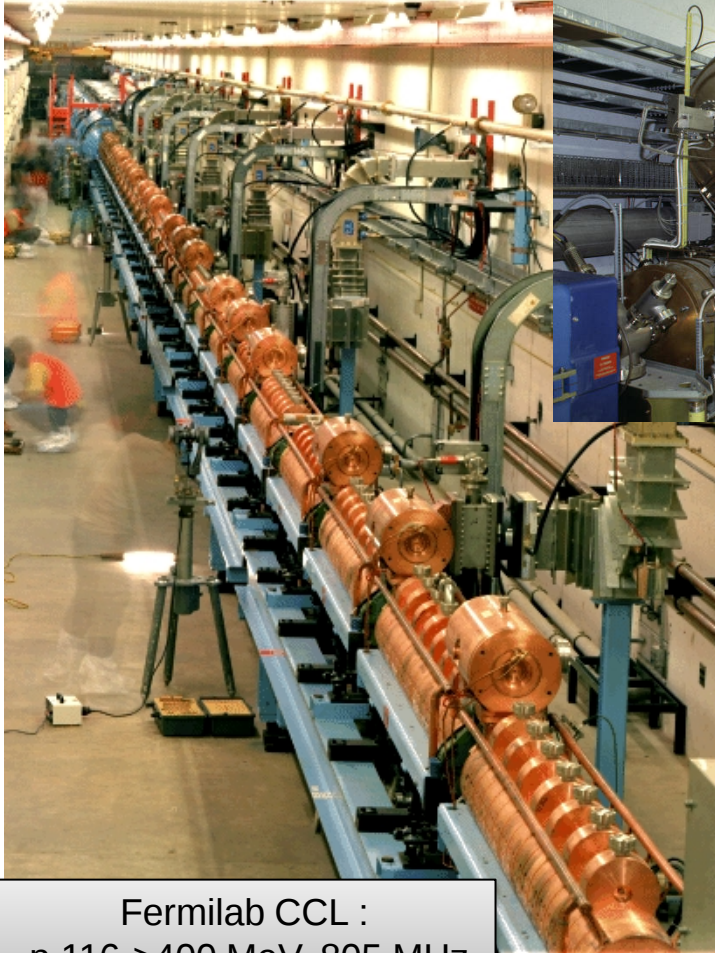


Unilac RFQ (GSI) :
2->120 keV/u, 36.1 MHz



Fermilab DTL :
-> 116 MeV, 425 MHz

2.9. Examples of RF accelerating cavities (2)



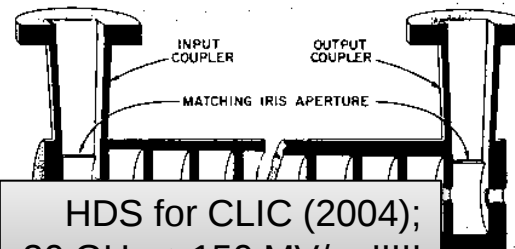
Fermilab CCL :
p,116->400 MeV, 805 MHz



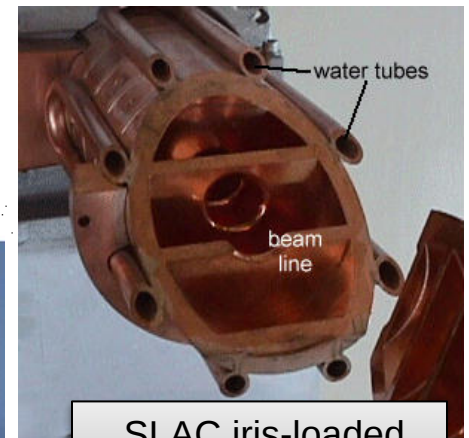
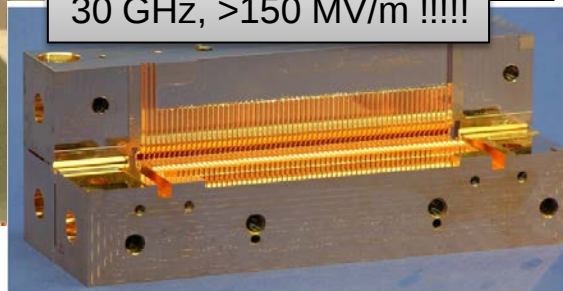
LEP1 cavities
(CERN), 352 MHz



Split-ring re-buncher
(TRIUMF), 35 MHz



HDS for CLIC (2004);
30 GHz, >150 MV/m !!!!!



SLAC iris-loaded
structure, 2.86 GHz

2.9. Examples of RF accelerating cavities (3)

Niobium elliptical cavities: size Vs frequency



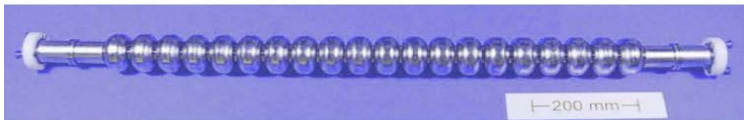
352 MHz
LEP



1300 MHz
TESLA

Spiral2 QWR, Nb,
 $\beta = 0.12$, 88 MHz

Cavities
 $\beta = 0.12$



3000 MHz
S-DALINAC



ANL Spoke cavity, Nb,
 $\beta = 0.4$, 345 MHz



Nb CESR-III cavity
(Cornell), 500 MHz



$\beta = 0.61$

SNS elliptical cavities,
Nb, 805 MHz, 15MV/m



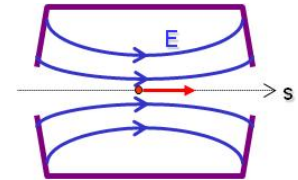
$\beta = 0.82$

2.10. Energy gain model

The energy gained by a particle in a cavity is:

$$\Delta W = \int qEz(s) \cdot \cos(\phi(s)) \cdot ds$$

$\phi(s)$ is the RF phase when particle is at s : $\phi(s) = \phi_0 + \omega \cdot t = \phi_0 + \frac{\omega}{c} \int_{s_0}^s \frac{ds}{\beta_z(s)}$



We define $V_0 = \int |Ez(s)| \cdot ds \longrightarrow$ The cavity **maximum voltage**

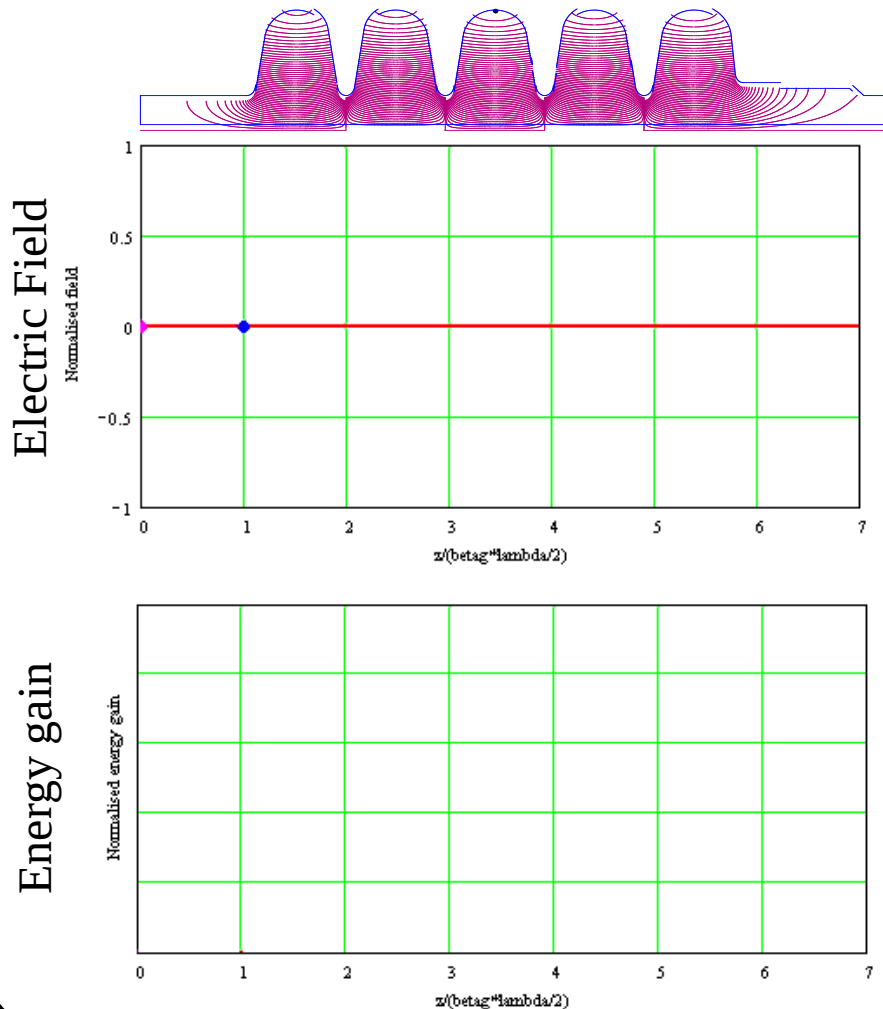
$T = \frac{1}{V_0} \left| \int Ez(s) \cdot e^{j\phi(s)} \cdot ds \right| \longrightarrow$ The **transit time factor**
(= Ez field ratio seen by the particle)

$\varphi_s = \arctan \left(\frac{\int Ez(s) \cdot \sin(\phi(s)) \cdot ds}{\int Ez(s) \cdot \cos(\phi(s)) \cdot ds} \right) \longrightarrow$ The **synchronous phase**
(= particle average phase with respect to RF)

Energy gain model: $\Delta W = |q| \cdot V_0 \cdot T(\bar{\beta}) \cdot \cos \varphi_s$

$V_0 T(\beta)$ is what is often called the **accelerating voltage** V_{acc} ($= E_{acc} L_{acc}$)

2.11. Ex: Transit time factor in a multi-cell cavity



Let's suppose the synchronous phase is chosen for maximum acceleration, i.e. $\phi_s=0$.

Thus $\Delta W = |q| V_0 \cdot T(\bar{\beta})$

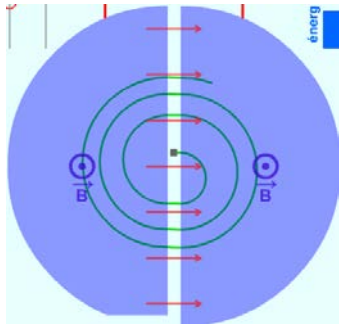
- Cavity Oscillating field
 - Field seen by a “synchronous” particle
 - Field seen by a non synchronous (too fast!) particle
-
- Hypothetical max energy gain qV_0
 - Energy gained by the “synchronous” particle : the transit time factor is $T \sim 0.8$
 - Energy gained by a non synchronous particle : the transit time factor is reduced

3. Synchronism & stability

3.1. Synchronism in cyclotrons

Cyclotron concept

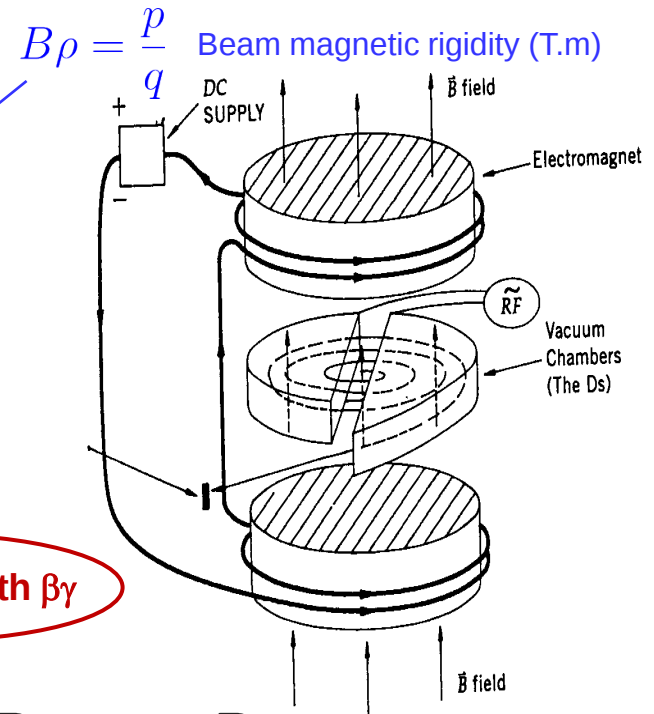
- > Constant magnetic field
- > Acceleration with constant RF frequency



$$\begin{aligned} B &= \text{cte} \\ f_{\text{RF}} &= \text{cte} \\ \rho &\neq \text{cte} \end{aligned}$$

$$\rho = \frac{p}{qB} = \frac{\beta\gamma \cdot m_0 c}{qB}$$

ρ increases with $\beta\gamma$



Condition for synchronism

$$\frac{T_{\text{RF}}}{2} = \frac{\pi \rho}{v} \rightarrow f_{\text{RF}} = \frac{v}{2\pi \rho} = \frac{\beta c \cdot B}{2\pi \cdot B \rho} = \frac{\beta c \cdot B q}{2\pi \cdot p} = \frac{B q}{2\pi \cdot \gamma m_0}$$

-> to keep $f_{\text{RF}} = \text{cte}$, we need $\gamma \cong 1$, i.e. a non-relativistic beam

-> if $\gamma > 1$, need for increasing B or decreasing the RF frequency with acceleration

3.2. Examples of cyclotrons (1)

1930: 1st cyclotron by E.O. Lawrence

11 cm diameter, 80 keV

1931: 28 cm, 1 MeV

1932: 69 cm, 4.8 MeV

1939: 1.5 m, 19 MeV

...

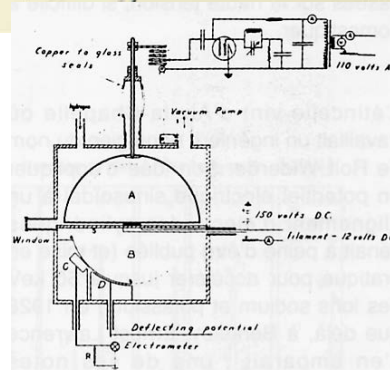
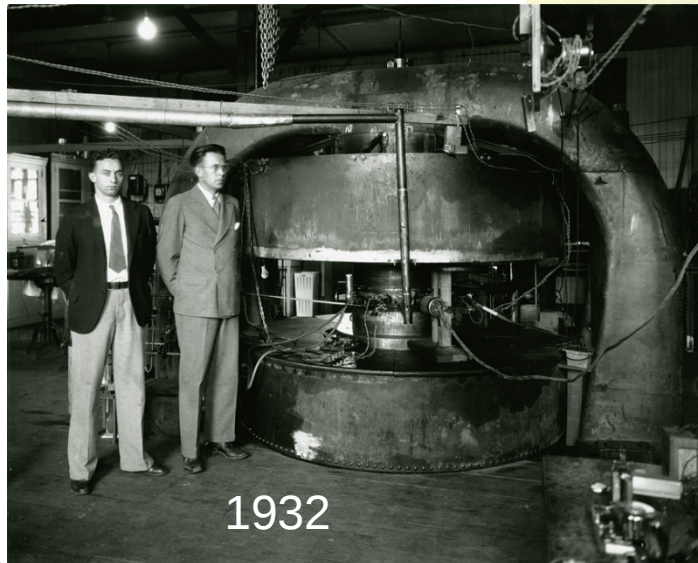
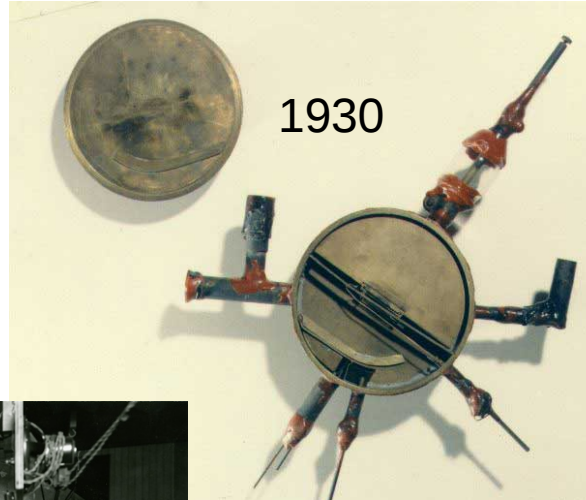
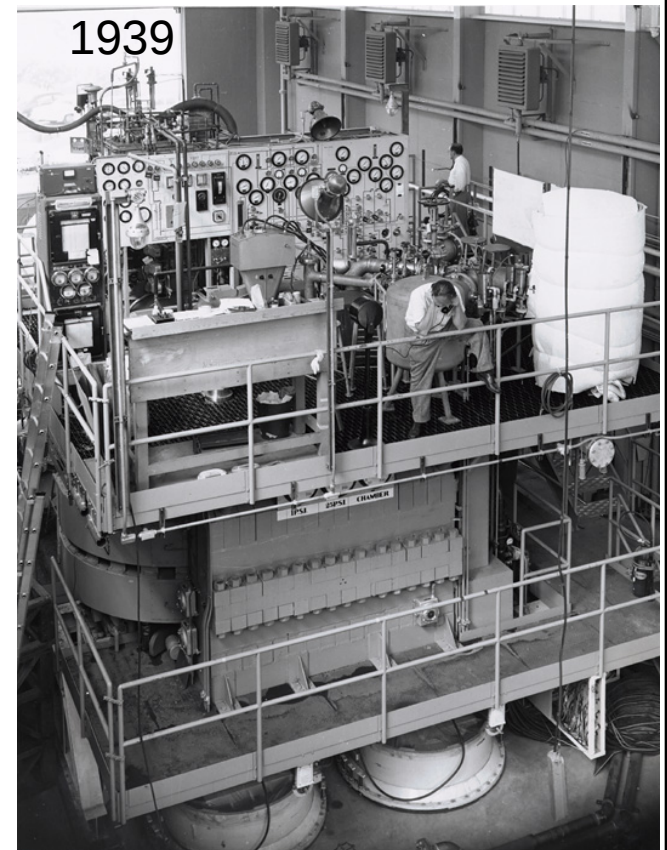
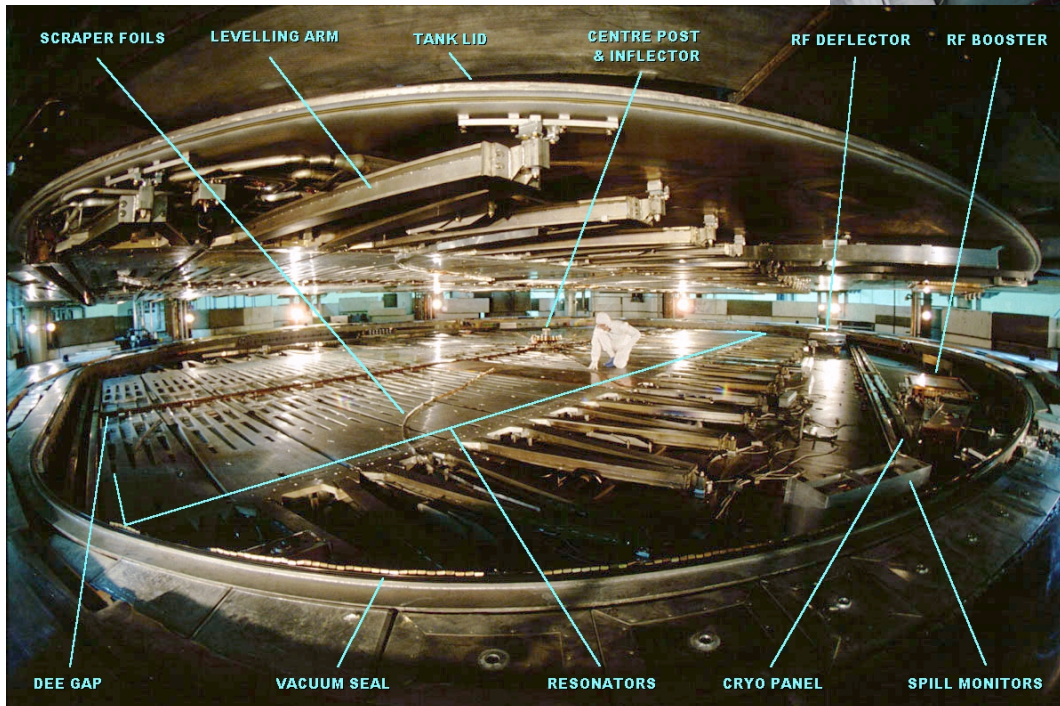
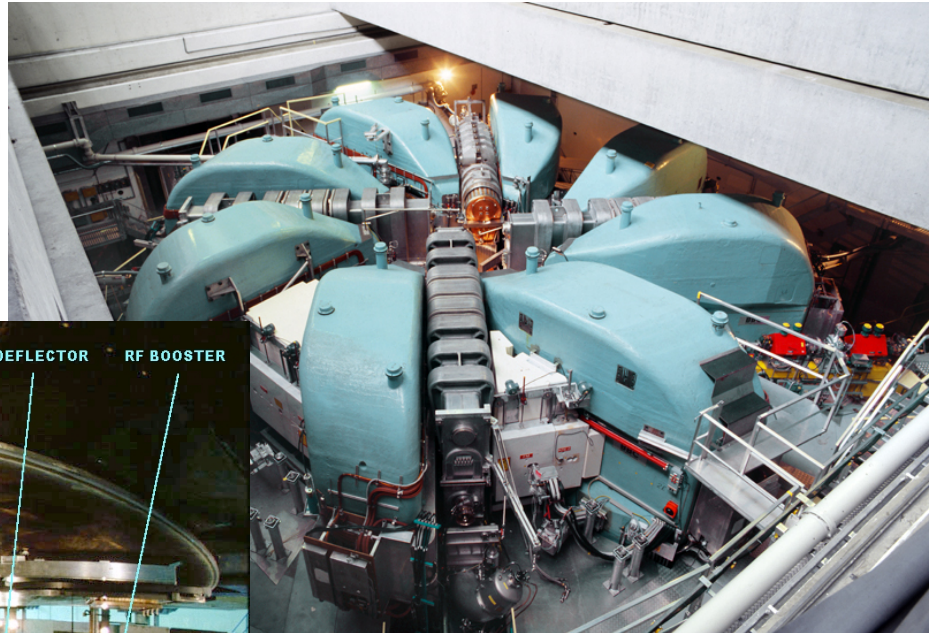


Figure 4
Schéma du premier cyclotron
Le diamètre du dee est de 5 pouces



3.2. Examples of cyclotrons (2)

View of the most powerful cyclotron worldwide at PSI (H⁺, 590MeV, 1.3MW, $f=50\text{MHz}$, 1T (1974)



Inside view of the biggest cyclotron worldwide at TRIUMF (H⁻, 520MeV, $f=23\text{ MHz}$, 0.6T (1974)

3.3. Synchronism in synchrotrons

Synchrotron concept

-> Acceleration at constant curvature radius ρ

$$\begin{array}{l} B \neq \text{cte} \\ f_{RF} \neq \text{cte} \\ \rho = \text{cte} \end{array}$$

$$B = \frac{p}{\rho q} = \frac{\beta \gamma \cdot m_0 c}{\rho q}$$

-> **B must be increased during acceleration**

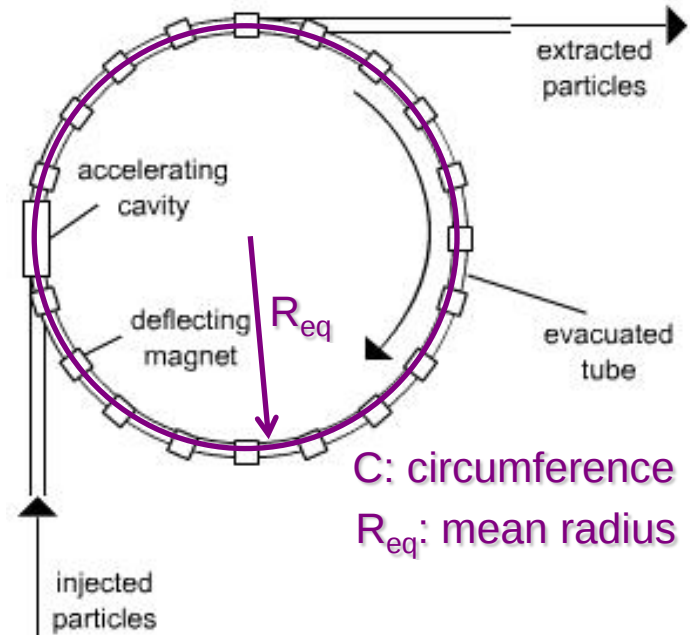
Condition for synchronism

$$h \cdot T_{RF} = \frac{C}{v} = \frac{2\pi R_{eq}}{\beta c} \rightarrow f_{RF} = \frac{\beta c}{2\pi R_{eq}} \cdot h$$

h: harmonic number
f_{rev}: revolution frequency

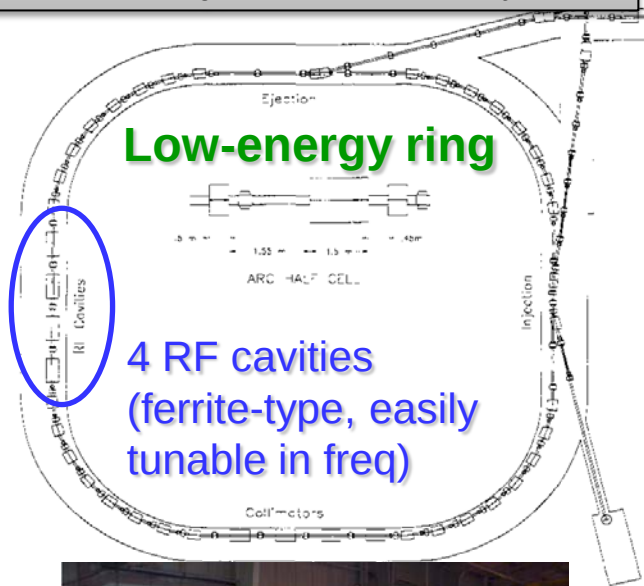
-> **f_{RF} must be increased during acceleration**

-> but when the particle is ultra-relativistic $\beta \simeq 1$, f_{RF} is kept practically constant

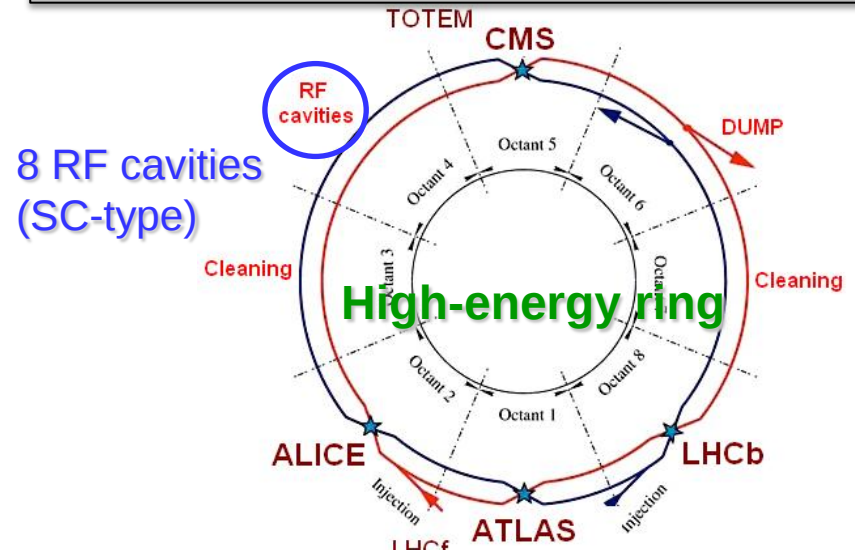


3.4. Examples of synchrotrons

SNS accumulator ring (ORNL):
proton, 1 GeV ($\gamma=2.06$), 0.79T
C=248m, $f_{\text{rev}}=1.058$ MHz, $\gamma_t=5.23$



LHC collider (CERN): proton,
450 GeV ($\gamma=480$) $\rightarrow$ 7 TeV ($\gamma=7460$), 8.33T
C=26.7km, $f_{\text{rev}}=11.25$ kHz, $\gamma_t=57.5$



3.5. Synchronism in linear accelerators (linacs)

Linac concept

-> A linac is a set of accelerating cells or of independent cavities along a linear path

Condition for synchronism

If cavities phases are coupled (RFQ, DTL, multi-cell cavities...)

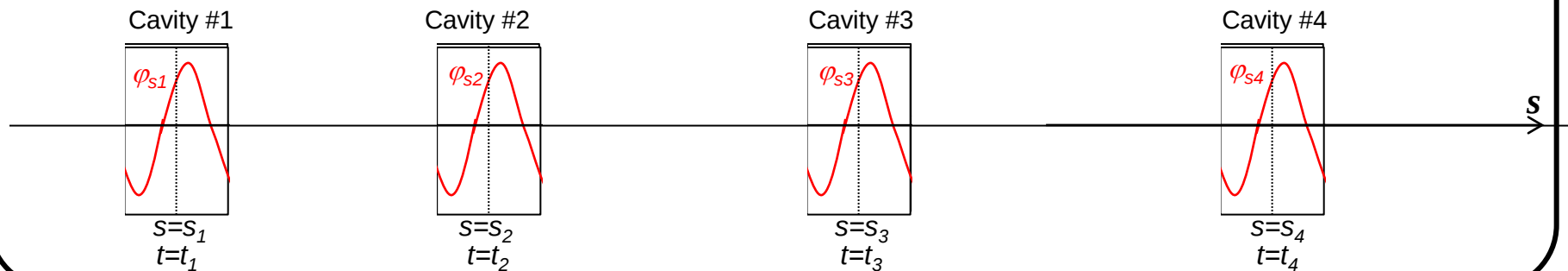
→ distances are adjusted for synchronism in the cavity design.

$$\frac{T_{RF}}{k} = \frac{L_i}{v_i} \quad \rightarrow \quad L_i = \frac{\beta_i c}{k f_{RF}} = \frac{\beta_i \cdot \lambda_{RF}}{k}$$

L_i : distance between cell i & i+1
v_i : particle speed between cell i & i+1
k : defines the RF mode (mode 2πi/k)

If cavities phases are independent (between DTL tanks, SC cavities linac...)

→ Cavities are phased for synchronism according to the distance between cavities



3.6. Choice of the synchronous phase (in linacs)

The synchronous phase is the most important parameter to choose during the accelerator design to provide both good acceleration and stability

1. The electric field must accelerate !!

-> Considering $\Delta W = |q| \cdot V_0 \cdot T(\bar{\beta}) \cdot \cos \varphi_s$, we get: $-90^\circ < \varphi_s < 90^\circ$

2. The acceleration must be stable

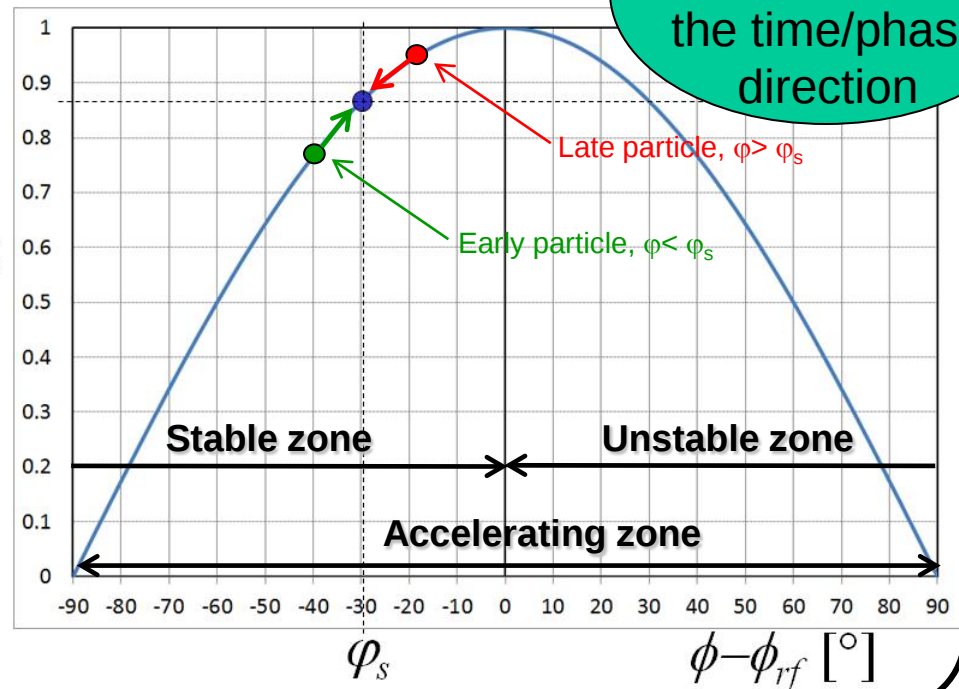
-> Late particles ● should gain more speed to overtake the ● particle: they should gain more energy (more E_z)

-> Early particles ● should gain less speed (and therefore less energy)

-> $E_z(t)$ must rise while particles are passing through the cavity, we get:

$$-180^\circ < \varphi_s < 0^\circ$$

In total, we need: $-90^\circ < \varphi_s < 0^\circ$



3.7. Particularity of circular machines

The criteria for stability is changed for synchrotron machines because a particle with higher energy will not always arrive earlier

-> higher energy = higher speed β , so it travels faster (ok...!^^)

-> BUT higher energy = higher momentum p , so its trajectory is longer

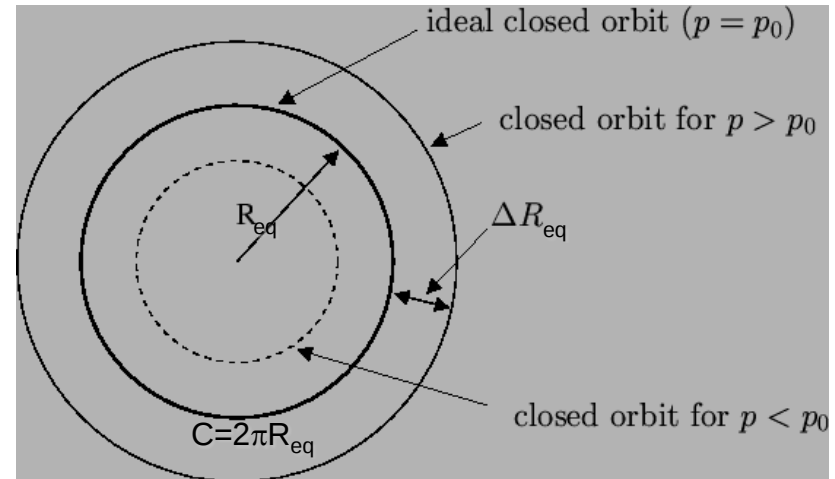
$$B\rho = \frac{p}{q}$$

To know if a particle with higher energy will arrive earlier or later, we look at the sign of **parameter η**

$$\eta = \frac{1}{\gamma^2} - \alpha$$

Where α is the momentum compaction

$$\alpha = \frac{dC/C}{dp/p} = \frac{dR_{eq}/R_{eq}}{dp/p}$$



$$\eta = 0 \quad \text{when} \quad \gamma = \frac{1}{\sqrt{\alpha}} = \gamma_t$$

γ_t = transition energy of the synchrotron

3.8. Choice of the synchronous phase (circular machines)

For $\eta > 0$ (i.e. $\gamma < \gamma_t$: low-energy rings),

the accelerator is governed by the speed change (like linacs where $\alpha=0$ i.e. $\eta = 1/\gamma^2 > 0$)

-> higher energy particles arrive earlier, like in the linac case

-> $E_z(t)$ must rise while particles are passing the RF cavity, we get: $-180^\circ < \varphi_s < 0^\circ$

In total (w/ acceleration), we need: $-90^\circ < \varphi_s < 0^\circ$

For $\eta < 0$ (i.e. $\gamma > \gamma_t$: high-energy rings),

the accelerator is governed by the trajectory/path change

-> higher energy particles arrive later

-> $E_z(t)$ must decrease while particles are passing the RF cavity: $0^\circ < \varphi_s < 180^\circ$

In total (w/ acceleration), we need: $0^\circ < \varphi_s < 90^\circ$

*Try to avoid crossing
the transition energy
during acceleration
if possible!*

3.9. Choice of the synchronous phase: summary

To complexify the picture, we use historically 2 different conventions for the synchronous phase definition...

Linac convention is COS...

$$\Delta W = |q| \cdot V_0 \cdot T(\bar{\beta}) \cdot \cos \varphi_s$$



Synchrotron convention is SIN...

$$\Delta W = |q| \cdot V_0 \cdot T(\bar{\beta}) \cdot \sin \varphi_s$$

	$\eta > 0$ (linac, low-energy synch.)		$\eta < 0$ (high-energy synch.)	
	$\Delta W \propto \cos \varphi_s$	$\Delta W \propto \sin \varphi_s$	$\Delta W \propto \cos \varphi_s$	$\Delta W \propto \sin \varphi_s$
Acceleration	$[-90^\circ, 90^\circ]$	$[0^\circ, 180^\circ]$	$[-90^\circ, 90^\circ]$	$[0^\circ, 180^\circ]$
Stability	$[-180^\circ, 0^\circ]$	$[-90^\circ, 90^\circ]$	$[0^\circ, 180^\circ]$	$[90^\circ, 270^\circ]$
Total	$[-90^\circ, 0^\circ]$	$[0^\circ, 90^\circ]$	$[0^\circ, 90^\circ]$	$[90^\circ, 180^\circ]$

How to choose a stable synchronous phase

4. Introduction to longitudinal dynamics

4.1. Longitudinal coordinates (φ, W)

Particles 6D vector coordinates

$$\begin{pmatrix} x \\ x' \\ y \\ y' \\ \varphi \\ W \end{pmatrix}$$

Transverse coordinates

- (x, y) are the particle transverse coordinates
- (x', y') are the particle transverse slopes $x' = \frac{dx}{ds}$ $y' = \frac{dy}{ds}$

Longitudinal coordinates

- φ is the phase at which the particle reaches position s ($\varphi = 2\pi f_{RF} \times t$)
- W is the particle kinetic energy at position s

Particle phase varies like:
$$d\varphi(s) = \frac{2\pi f_{RF}}{\beta(s) c} \cdot ds$$

Particle energy varies like:
$$dW(s) = qE_z(s) \cdot \cos(\varphi(s) - \varphi_{RF}) \cdot ds$$

*phase relative to
the RF phase in
cavities*

Longitudinal electric field in cavities

4.2. Reference to synchronous particle

The synchronous particle is a perfect virtual particle that travels on the reference trajectory and is always in perfect synchronism with cavities' RF fields

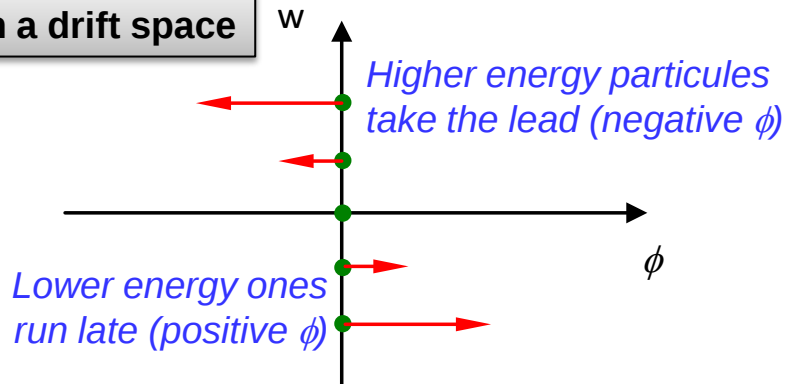
- The phase & energy of the synchronous particle are set by design: $\varphi_s(s)$, $W_s(s)$
- Beam particles are therefore referred to this synchronous particle

$$\begin{cases} \phi(s) = \varphi(s) - \varphi_s(s) \\ w(s) = W(s) - W_s(s) \end{cases}$$

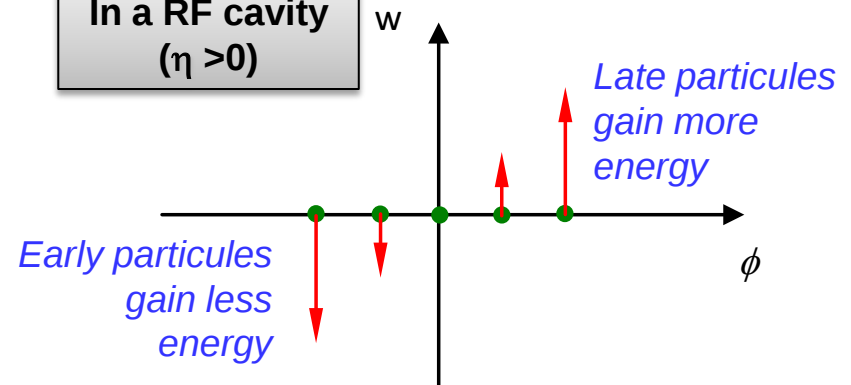
(ϕ, w) is the longitudinal phase space

Examples of trajectories in the longitudinal phase space

In a drift space



In a RF cavity ($\eta > 0$)



4.3. Synchrotron equations

Considering a continuous accelerating channel, the evolution of the variables ϕ and w can be derived:

$$\left\{ \begin{array}{l} \frac{d\phi}{ds} = -\frac{2\pi \cdot \eta \cdot f_{RF}}{\beta_s^3 \gamma_s m_0 c^3} \cdot w \\ \frac{dw}{ds} = qE_0 T \cdot (\sin\varphi_s \cdot (\cos\phi - 1) + \cos\varphi_s \cdot \sin\phi) \end{array} \right.$$

$$\eta = \frac{1}{\gamma^2} - \alpha$$

Synchrotron
equations

= Equation of a non-linear oscillator

These equations can be rewritten as:

$$\left\{ \begin{array}{l} \frac{d\phi}{ds} = -\frac{\partial H}{\partial w} \\ \frac{dw}{ds} = \frac{\partial H}{\partial \phi} \end{array} \right.$$

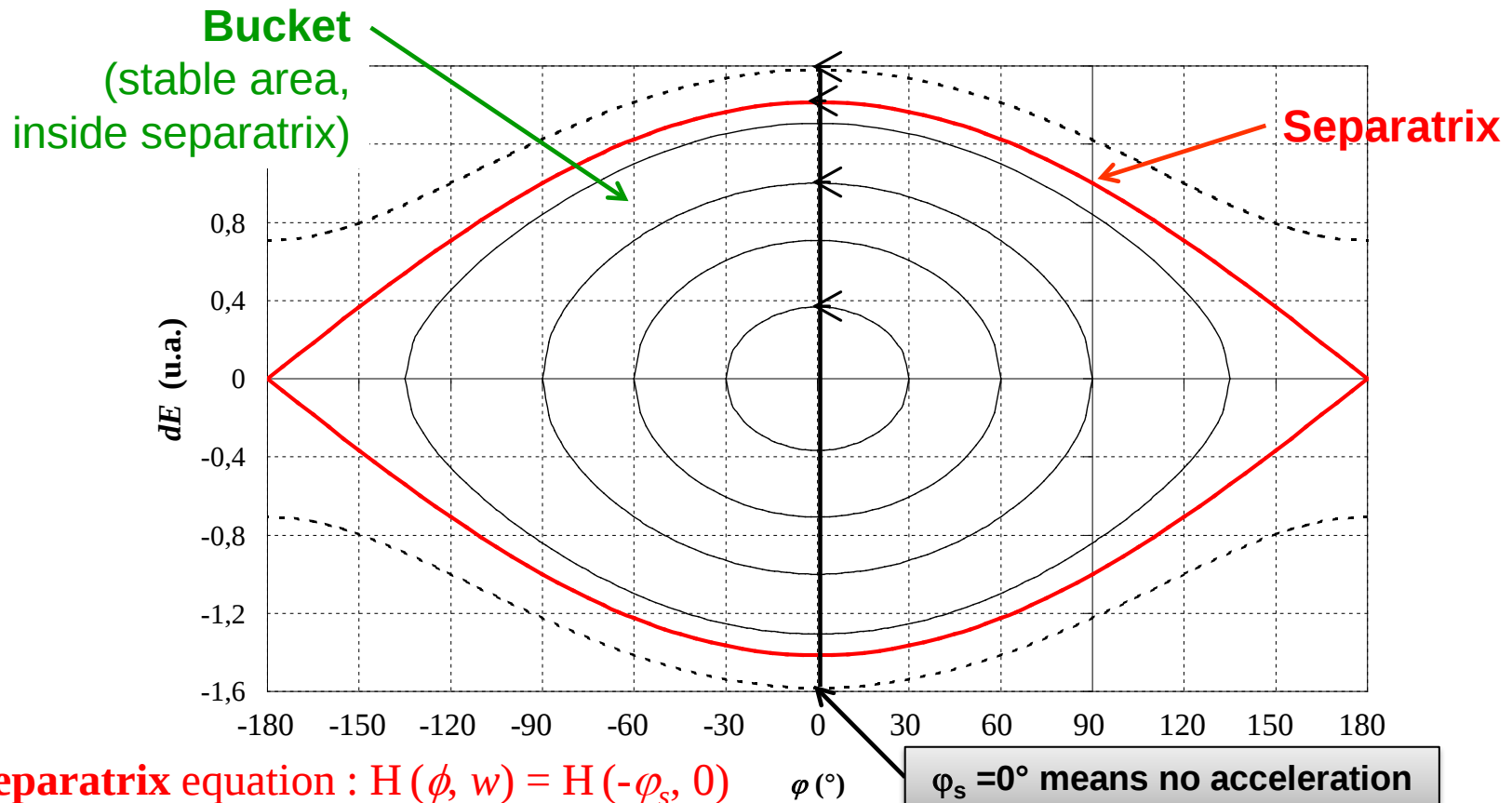
Particles follow
curves for which
 $H = C^{\text{st}}$

Where H is the longitudinal Hamiltonian of the movement, which is an invariant

$$H(\phi, w) = \frac{\pi \cdot \eta \cdot f_{RF}}{\beta_s^3 \gamma_s m_0 c^3} \cdot w^2 - qE_0 T \cdot (\sin\varphi_s \cdot (\phi - \sin\phi) - \cos\varphi_s \cdot (1 - \cos\phi))$$

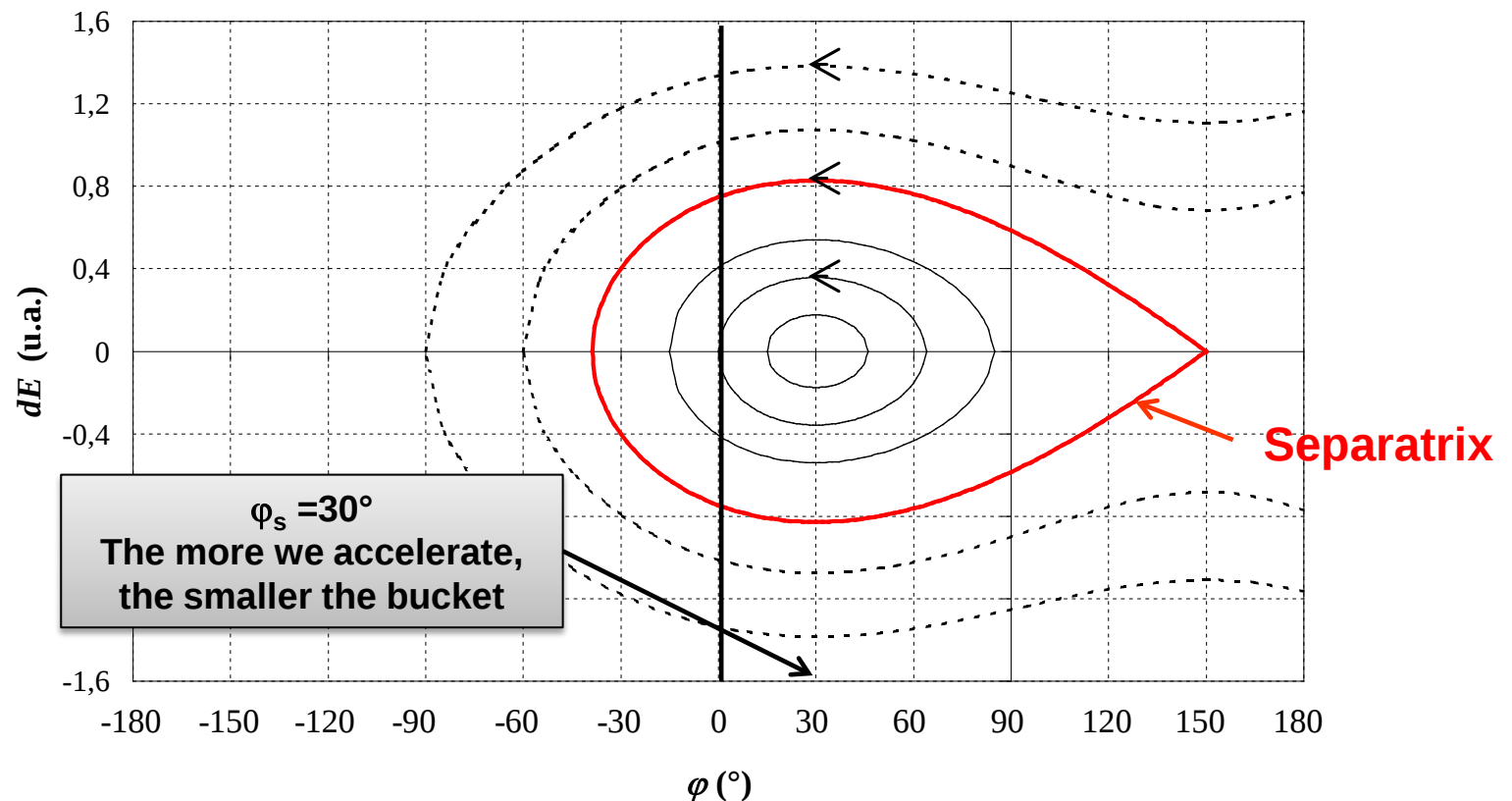
4.4. Trajectories in the longitudinal phase space (1)

Trajectories for a 0° synchronous phase (sinus « ring-convention ») and $\eta > 0$
(-90° in cosinus « linac-convention »)



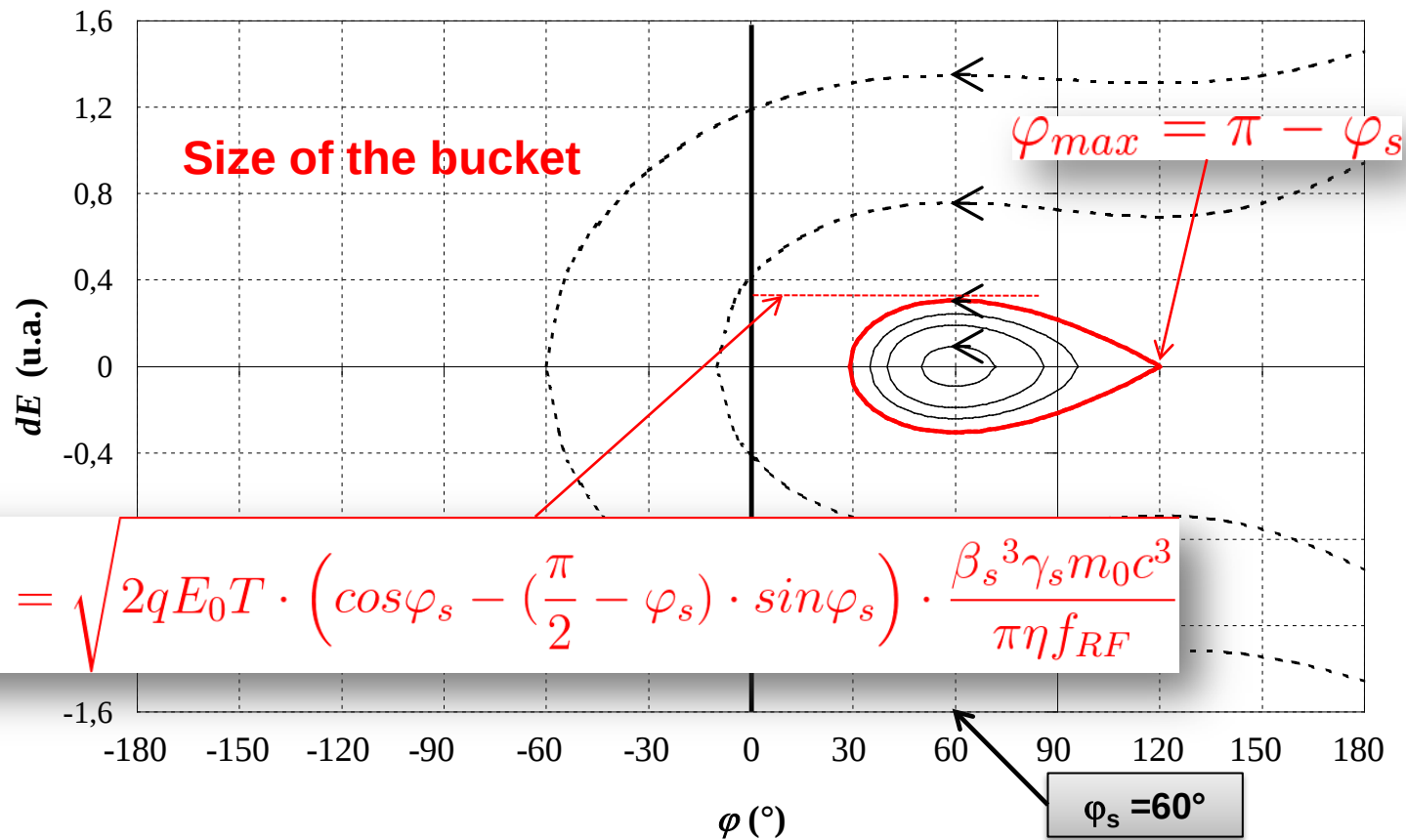
4.4. Trajectories in the longitudinal phase space (2)

Trajectories for a 30° synchronous phase (sinus « ring-convention ») and $\eta > 0$
(-60° in cosinus « linac-convention »)



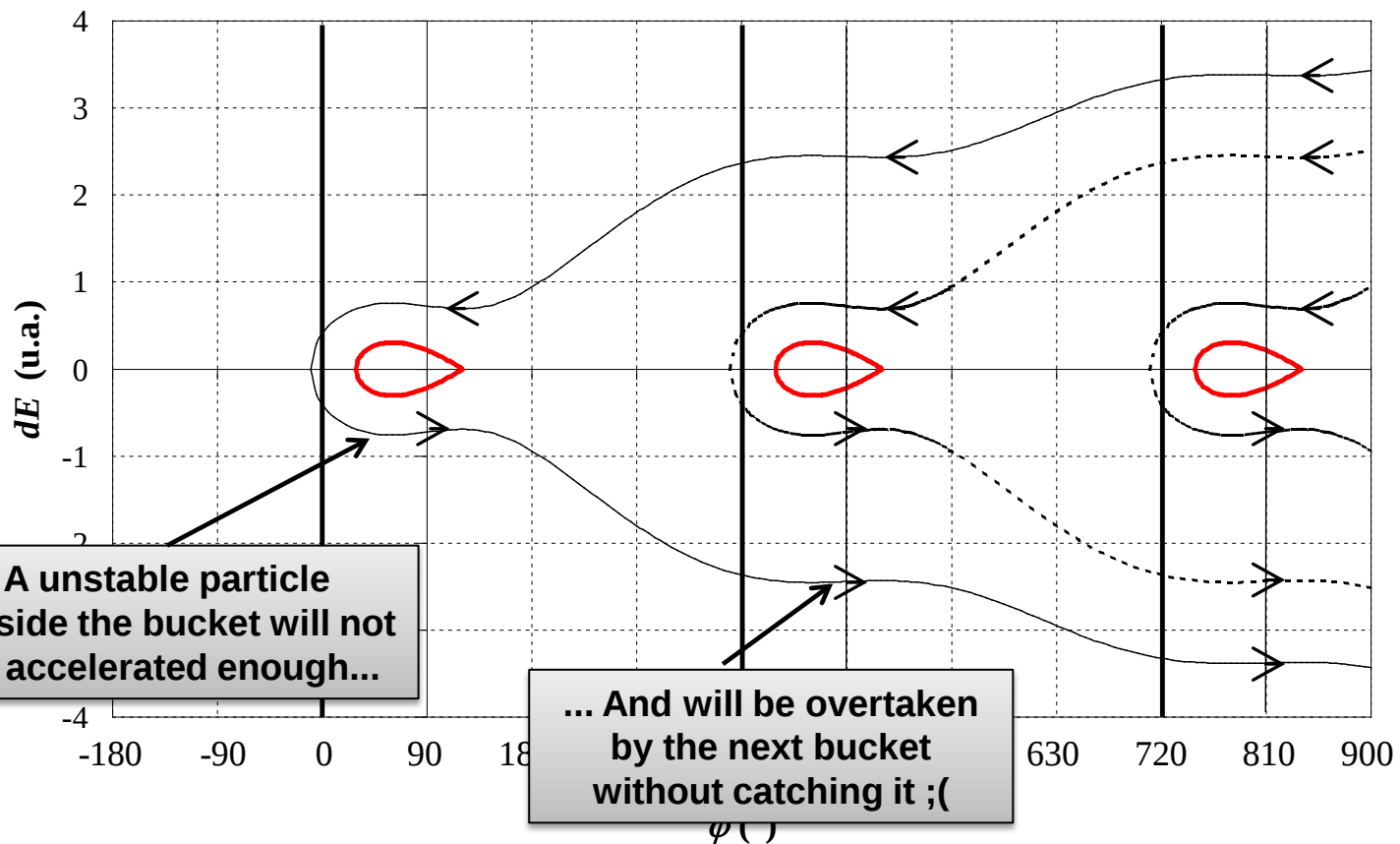
4.4. Trajectories in the longitudinal phase space (3)

Trajectories for a 60° synchronous phase (sinus « ring-convention ») and $\eta > 0$
 (-30° in cosinus « linac-convention »)



4.4. Trajectories in the longitudinal phase space (3)

Trajectories for a 60° synchronous phase (sinus « ring-convention ») and $\eta > 0$
(-30° in cosinus « linac-convention »)



4.5. Treatment at small amplitudes

For small amplitudes (i.e. $\phi \ll 1$: in the center of the bucket), the synchrotron equations can be linearized:

$$\frac{d\phi}{ds} = -\frac{2\pi \cdot \eta \cdot f_{RF}}{\beta_s^3 \gamma_s m_0 c^3} \cdot w = -\frac{\partial H}{\partial w} \quad \frac{dw}{ds} = qE_0 T \cdot \phi \cdot \cos\varphi_s = \frac{\partial H}{\partial \phi}$$

It comes:
$$\frac{d^2\phi}{ds^2} = -\frac{2\pi \cdot \eta \cdot f_{RF} \cdot qE_0 T \cdot \cos\varphi_s}{\beta_s^3 \gamma_s m_0 c^3} \cdot \phi$$

= Equation of a linear oscillator

-> Particles **oscillate around the synchronous particle** with angular frequency:

$$k_0 = \sqrt{\frac{2\pi f_{RF} \cdot \eta \cdot qE_0 T \cdot \cos\varphi_s}{\beta_s^3 \gamma_s m_0 c^3}}$$

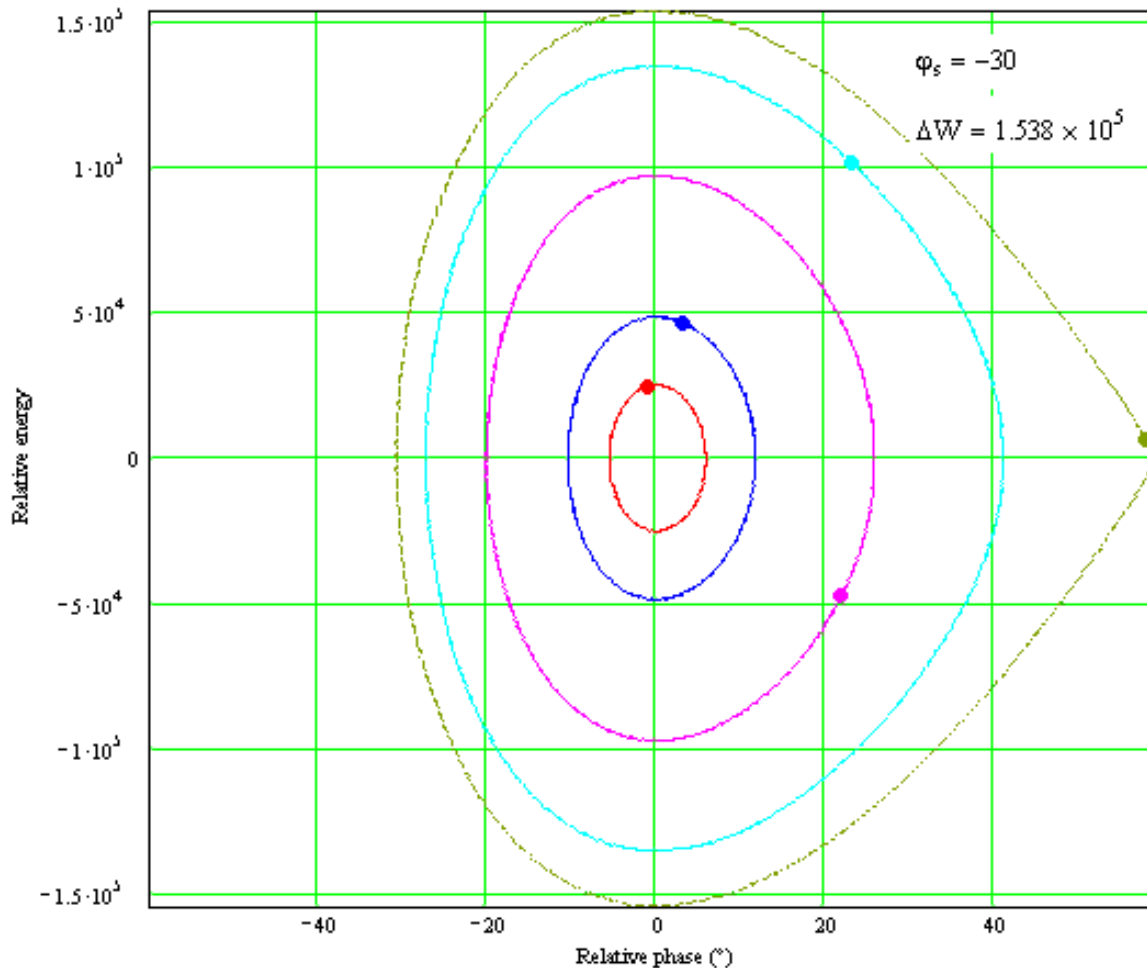
Synchrotron
angular frequency

or synchrotron
phase advance

-> Curves for which $H = C^{\text{st}}$ become **ellipses** in the longitudinal phase space (ϕ, w)

$$\frac{\pi \cdot \eta \cdot f_{RF}}{\beta_s^3 \gamma_s m_0 c^3} \cdot w^2 + \frac{qE_0 T \cdot \cos\varphi_s}{2} \cdot \phi^2 = Cte$$

4.6. Synchrotron oscillations (at constant $\beta\gamma$)



1st order matrix model
is valid for $\phi \ll 1$

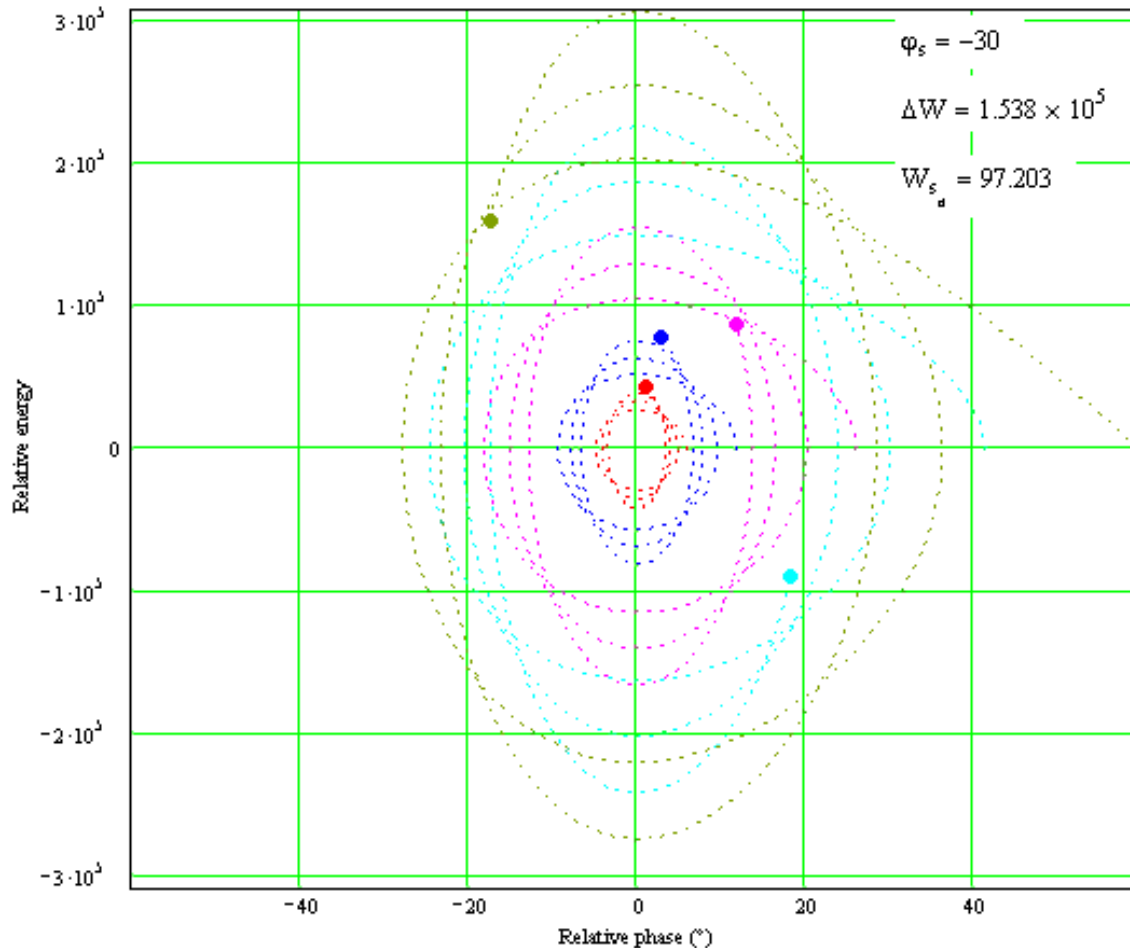
In the inner part of the bucket ($\phi \ll 1$):
Behaviour of a linear oscillator at the synchrotron angular frequency

$$k_0 = \sqrt{\frac{2\pi f_{RF} \cdot \eta \cdot q E_0 T \cdot \cos \phi_s}{\beta_s^3 \gamma_s m_0 c^3}}$$

In the outer part of the bucket:
Non linear behaviour, the particles oscillates more & more slowly

We assume here $E_z = Cst$, $\phi_s = -30^\circ$ and $\beta_s \gamma_s = Cst$

4.7. Synchrotron oscillations (w/ increasing energy)



Increasing $\beta\gamma$, the amplitude of the oscillations are:

- > REDUCED in phase
- > INCREASED in energy
(by a factor $(\beta\gamma)^{3/4}$)

= adiabatic damping

BUT the surface of each $H=\text{cte}$ trajectory is kept constant

(that means that the longitudinal emittance is a priori kept constant with increasing energy)

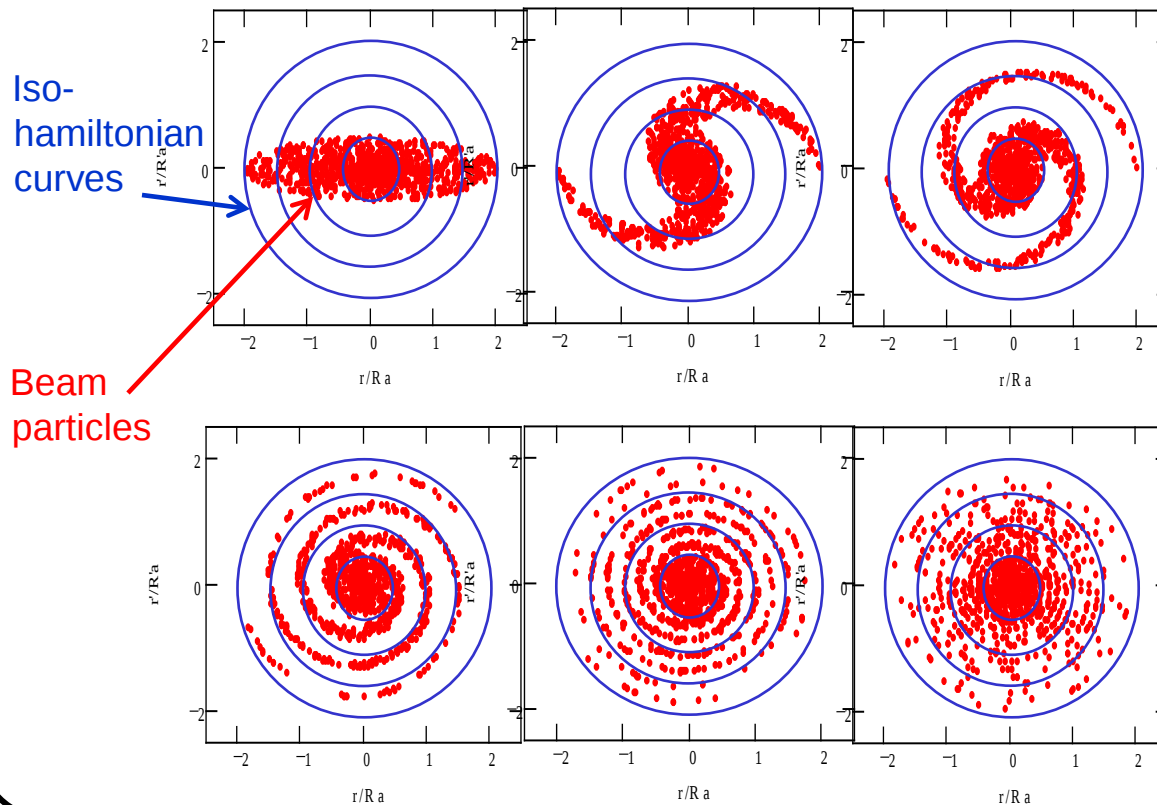
We assume here $E_z = Cst$, $\phi_s = -30^\circ$ and $\beta_s\gamma_s \neq Cst$

4.8. Filamentation in longitudinal phase space

All the beam particles are thus traveling on the $H = C^{\text{st}}$ curves in the (ϕ, w) space

= *trajectories at frequency k_0 if the forces are linear (inner bucket)*

= *trajectories at lower frequency when the forces become non-linear (outer bucket)*



=> If the beam is not correctly matched to $H=\text{cte}$ curves, **filamentation** is quickly observed

The beam longitudinal rms emittance is then increasing

Merci pour votre attention!

Et merci à Nicolas Pichoff, auteur de qqes-unes des animations ;)